Model to Model Transformation Tool for the DPF Workbench

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Abstract

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Model transformations has a major part in Model Driven Development. This thesis presents the DPF Transformation Editor, an extension to the DPF Workbench that specifies model to model transformations for DPF specifications. There are quite the collection of model transformation environments with diverse approaches to model transformations. The purpose of this thesis is to see if we can integrate an existing model transformation environment with DPF that supports translations between different modeling languages. Some of these approaches to model transformations are explored in a comparison of three model transformation environments: 1) Henshin representing traditional graph transformation on Ecore models, 2) Attributed Graph Grammar (AGG) representing traditional graph transformation, and 3) Atlas Transformation Language (ATL) representing model transformation on Ecore models. Our case study involves a specific exogenous model transformation that translates an UML activity diagram to a Petri Net model. The main focus with this comparison is to find a transformation language that together with the DPF Transformation Editor provides a viable solution to model to model transformations for DPF specifications.
Acknowledgements

The acknowledgements and the people to thank go here, don’t forget to include your project advisor...
Contents

Abstract i

Acknowledgements ii

List of Figures vi

List of Tables viii

Abbreviations ix

1 Introduction 1
  1.1 Motivation ........................................ 1
  1.2 The structure of the Thesis ...................... 2

2 Background 3
  2.1 Model Driven Engineering ....................... 3
    2.1.1 Model Driven Architecture .................. 5
  2.2 Modeling Languages ................................ 8
    2.2.1 Meta-modeling .................................. 9
    2.2.2 Constraints ...................................... 11
  2.3 Language Workbenches .............................. 12
    2.3.1 EMF ........................................... 13
  2.4 Diagram Predicate Framework .................... 14
  2.5 DPF Workbench ..................................... 17

3 Model Transformation 19
  3.1 Basic concepts of model transformation ........... 19
    3.1.1 Layer of Abstractions ....................... 20
  3.2 Model Transformations in MDE ..................... 22
  3.3 Existing Environments .............................. 23
  3.4 Classification of a model transformation ......... 25
    3.4.1 Specification .................................. 26
    3.4.2 Transformation Rules ......................... 26
    3.4.3 Rule Application Control ..................... 28
    3.4.4 Rule Organization .............................. 29
4 Problem Specification 37
  4.1 Problem Specification .................................... 37
  4.2 Three different model transformation environments ............ 39
      4.2.1 The Attributed Graph Grammar System ................ 40
      4.2.2 The Henshin Project ............................... 45
      4.2.3 ATL Transformation Language ....................... 50
  4.3 Model transformation environment for DPF ..................... 56

5 Problem Solution 59
  5.1 Integrate Henshin with DPF ................................ 59
  5.2 Henshin meta-model ...................................... 61
  5.3 DPF Transformation Editor ................................. 63
  5.4 Generate Correspondence Graph ................................ 65
  5.5 Generate Henshin Rules .................................... 66
      5.5.1 Traceable links .................................... 69
  5.6 Apply Model Transformation ................................ 70
      5.6.1 Rule Application Control ........................... 70
      5.6.2 The Transformed Model ............................. 71

6 Evaluation 72
  6.1 Evaluation of Solution ................................... 72
  6.2 Test case with the DPF Transformation Editor .................. 73
  6.3 Comparison with other editor tools ........................ 73
      6.3.1 Editing Transformation Rules ....................... 75
      6.3.2 Meta-modeling .................................... 76
      6.3.3 Transformation Rules ................................ 77
      6.3.4 Rule Scheduling ................................... 77
      6.3.5 Rule Organization .................................. 78
      6.3.6 Source - Target Relationship ........................ 79
      6.3.7 Directionality ..................................... 79
      6.3.8 Tracing ........................................... 80
      6.3.9 Translating the instance model ..................... 80

7 Conclusion 82
  7.1 Future Work ............................................. 83
      7.1.1 Endogenous Model Transformations .................... 83
      7.1.2 Making the Model Transformations constraint aware .... 83
      7.1.3 Verification of target modeling formalism predicates ... 84
## List of Figures

<table>
<thead>
<tr>
<th>Figure</th>
<th>Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.1</td>
<td>Rational Unified Process</td>
<td>4</td>
</tr>
<tr>
<td>2.2</td>
<td>Software Development with MDA</td>
<td>6</td>
</tr>
<tr>
<td>2.3</td>
<td>The three levels of modeling abstraction for MDA</td>
<td>7</td>
</tr>
<tr>
<td>2.4</td>
<td>Main ingredients of a modeling language</td>
<td>8</td>
</tr>
<tr>
<td>2.5</td>
<td>Example of a model and meta-model</td>
<td>9</td>
</tr>
<tr>
<td>2.6</td>
<td>Meta Object Facility</td>
<td>10</td>
</tr>
<tr>
<td>2.7</td>
<td>Simple model with constraints</td>
<td>11</td>
</tr>
<tr>
<td>2.8</td>
<td>Intended use of language workbenches</td>
<td>13</td>
</tr>
<tr>
<td>2.9</td>
<td>Components of language workbenches</td>
<td>13</td>
</tr>
<tr>
<td>2.10</td>
<td>Ecore model represented by Ecore Tools</td>
<td>14</td>
</tr>
<tr>
<td>2.11</td>
<td>A specification and some predefined diagrammatic predicate attached</td>
<td>15</td>
</tr>
<tr>
<td>2.12</td>
<td>Modeling formalism in DPF</td>
<td>16</td>
</tr>
<tr>
<td>2.13</td>
<td>OMG's layers of meta-modeling and multilayer modeling</td>
<td>17</td>
</tr>
<tr>
<td>2.14</td>
<td>DPF Editor in multi-layer meta-modeling hierarchy</td>
<td>18</td>
</tr>
<tr>
<td>3.1</td>
<td>Basic Model Transformation</td>
<td>20</td>
</tr>
<tr>
<td>3.2</td>
<td>Vertical and Horizontal model transformations</td>
<td>22</td>
</tr>
<tr>
<td>3.3</td>
<td>Model Transformations in MDA</td>
<td>23</td>
</tr>
<tr>
<td>3.4</td>
<td>Domain Analysis of Model Transformations</td>
<td>25</td>
</tr>
<tr>
<td>3.5</td>
<td>Feature diagram for transformation rules</td>
<td>26</td>
</tr>
<tr>
<td>3.6</td>
<td>Feature diagram a domain</td>
<td>26</td>
</tr>
<tr>
<td>3.7</td>
<td>Category Theory</td>
<td>32</td>
</tr>
<tr>
<td>3.8</td>
<td>Basic concepts of graph homomorphism</td>
<td>32</td>
</tr>
<tr>
<td>3.9</td>
<td>Idea of graph transformation</td>
<td>34</td>
</tr>
<tr>
<td>3.10</td>
<td>The Double Pushout approach</td>
<td>34</td>
</tr>
<tr>
<td>3.11</td>
<td>A Negative application condition</td>
<td>35</td>
</tr>
<tr>
<td>3.12</td>
<td>The Double Pushout approach with NAC</td>
<td>36</td>
</tr>
<tr>
<td>4.1</td>
<td>Specification relationship with core meta-model</td>
<td>38</td>
</tr>
<tr>
<td>4.2</td>
<td>Abstract syntax of the source model</td>
<td>39</td>
</tr>
<tr>
<td>4.3</td>
<td>Abstract syntax of the target model</td>
<td>40</td>
</tr>
<tr>
<td>4.4</td>
<td>Graphical Editor for AGG</td>
<td>41</td>
</tr>
<tr>
<td>4.5</td>
<td>Type graph in AGG</td>
<td>42</td>
</tr>
<tr>
<td>4.6</td>
<td>Tree based editor in AGG</td>
<td>43</td>
</tr>
<tr>
<td>4.7</td>
<td>Representation of a rule in AGG</td>
<td>44</td>
</tr>
<tr>
<td>4.8</td>
<td>The Henshin Model Editor</td>
<td>46</td>
</tr>
<tr>
<td>4.9</td>
<td>The Henshin graphical editor</td>
<td>48</td>
</tr>
<tr>
<td>4.10</td>
<td>A Sequential Unit in Henshin</td>
<td>49</td>
</tr>
</tbody>
</table>
List of Figures

4.11 Model transformation for Atlas transformation language .................. 51
4.12 Simple rules for ATL .................................................. 52
4.13 Example of a matched rule in ATL .................................... 54
4.14 Internal infrastructure for ATL ......................................... 55
4.15 Proposed solution for integration of AGG .............................. 56

5.1 Integrating Henshin with DPF .......................................... 59
5.2 Work flow for the solution ................................................ 60
5.3 Henshin meta-model for a transformation rule ......................... 61
5.4 Henshin relationship with Ecore .......................................... 62
5.5 Model for the DPF Transformation Editor .............................. 63
5.6 The three subgraphs for a transformation rule ......................... 64
5.7 Specification for the correspondence objects .......................... 65
5.8 Relationship between node and arrow in DPF .......................... 67
5.9 How we want to handled types for a DPF model ....................... 68
5.10 How to handle node types for a rule in Henshin ..................... 68
5.11 The transformed specification ......................................... 71

6.1 Simplified joined specification ........................................... 73

7.1 Simplified joined specification .......................................... 84
List of Tables

3.1 Example model transformations. ........................................ 21
6.1 Comparing model transformation tools. ............................ 74
Abbreviations

EMF  Eclipse Modelling Framework
EMP  Eclipse Modelling Project
GEF  Graphical Editing Framework
SPO  Single Pushout Approach
DPO  Double Pushout Approach
NAC  Negative Application Condition
PAC  Positive Application Condition
LHS  Left Hand Side
RHS  Right Hand Side
DPF  Diagram Predicate Framework
MDE  Model Driven Engineering
UML  Unified Modeling Language
RUP  Rational Unified Process
DSML  Domain Specific Modeling Language
CIM  Computation-Independent Model
PIM  Platform-Independent Model
PSM  Platform-Specific Model
OMG  Object Management Group
MOF  Meta Object Facility
OCL  Object Constraint Language
CPU  Central Processing Unit
ATL  ATLAS Transformation Language
MDA  Model Driven Architecture
AGG  Attributed Graph Grammar
QVT  Query View Transformation
Abbreviations

MDSE Model Driven Software Engineering
MMT Model-to-Model Transformation
For/Dedicated to/To my...
Chapter 1

Introduction

1.1 Motivation

Model Driven Engineering (MDE) has been around for quite some time now and is by no references new to computer science. The use of miniatures or a visual representation of a system to provide an explanation of some problem has always been around. To be able to draw an abstraction of a complex system or problem on a piece of paper to supplement a explanation often tends to make the explanation easier to understand. The explanation does not necessary have to be difficult to understand, but a miniature or a model will make the explanation easier to understand. This was how i experienced the use of models during my bachelor period. That they were meant to represent abstractions of systems and programs.

When i started to work on my master program we started to visit more concepts around MDE and how we can use models and model transformations to automate a software application process. The first tools that supported this vision of MDE were the Computer-Aided Software Engineering (CASE) and was developed in the 1980s. Tools like CASE thrived to achieve this vision of MDE to be a fully usable approach to software development. This meant to use models as the major artifact in a software application. Where in the initially phases of a software development models would provide an abstraction of the problem and evolve with more details through the development process. These models would evolve to more specific technology based abstractions with the help of model transformations and in the end fully executable software implementation of the application would be generated.

As the years went by MDE has become a strong foundation to create domain specific modeling languages. With the possibility to define meta-models with constraints proved to be a viable solution to create the structure of a modeling language or a specific modeling language. Based on this the Object Management Group (OMG) created the Unified Modeling Language[1] (UML) that became a standard for creating modeling languages. Many modeling tools adapts UML in the process of creating a domain specific modeling environment.
Lately a diagrammatic approach to utilize the visions of MDE has become more popular amongst MDE researchers. Where the focus is more on graphs and graph theory. The Diagram Predicate Framework (DPF) is such a framework that take advantage of category theory and graph transformations to provide a formal approach to meta-modeling, model transformation and model management. For this thesis we have the following research question, *Can we extend the DPF Workbench with an editor that support model to model transformations between different Domain Specific Modeling Languages.*

### 1.2 The structure of the Thesis

This thesis is structured with the following sections.

**Chapter 2.** This chapter is meant to explain background material to this thesis. Where we discuss the visions of model driven engineering. We also consider a specific design approach to these visions. Then we discuss modeling languages and their role in language workbenches. At the end of the chapter we go into detail on the DPF environment.

**Chapter 3.** This chapter introduces model transformation in general. We discuss the basic concepts of model transformations and how they are used in MDE. Later in the chapter we try to classify model to model transformations and explain design choices behind the graph based approach to achieve this.

**Chapter 4.** In chapter 4 we describe the problem at hand and how we want to approach this. We consider three different model transformation tools and find the tool that is best suited to be integrated with DPF.

**Chapter 5.** This chapter describes how we created a model to model transformation environment for the framework. We describe the model transformation environment we integrated with DPF and how this works with the transformation editor.

**Chapter 6.** Here we want evaluate our solution and also discuss functionality that should be included in future versions of the tool. Then we want to compare our solution with existing transformation tools and provide a conclusion at the end.

**Chapter 7.** In this chapter we provide a conclusion for this master thesis. We also mention some future work for the transformation tool.
Chapter 2

Background

2.1 Model Driven Engineering

When a new software is created it has always been a goal to produce high quality code at the lowest possible cost. To plan a software development project from its initial start to delivering a finished product can seem like an impossible thing to do. Because a software development cycle rarely goes as initially planned. Changes do occur, both in delivering high quality code and keeping the costs down. Traditionally when model driven engineering (MDE) is used, people think about models, for example activity diagrams and class diagrams from the popular modeling language, UML. Where models is used to raise the level of abstraction for the problem specification and describing how a software should be implemented. For these software development processes models are indirectly used in the creation of software. This means that models are primarily used as a reference when implementing an application.

A model is an abstraction of a system, and has its origin from Latin, *modulus* that means measure or standard. A model can either be used to represent a system before it is created or to describe some major aspects of a system or a concept. When we hear the term model, many will think that it is a miniature that consists of a set of nodes and arrows. But it is important to consider that a model can also be represented by text.

If we consider traditionally software development processes, then models are primarily used in application requirements and use-case diagrams specify what the customer wants. Then developers can specify models to detect important functionality of the application. The software developer may for example create flow charts, sequence diagrams, activity diagrams, class diagrams, etc, to describe how the system should be implemented. A model for system architecture can also be initialized for developers to handle design choices. Rational Unified Process[2] (RUP) is an example of a software development process that is build around extensive use of models in their initial planning phase. RUP was initially created by Rational Software Corporation[3] in 2006 and was later acquired by International Business Machines Corporation[4]. This is an iterative software development process and the purpose of RUP is to be an adaptable process framework where the software project teams decide the elements that are required for a development cycle. Figure 2.1 explains the four different phases, Inception, Elaboration, Construction and Transition, with different iterations for each phase that RUP
provides. The Inception phase and the Elaboration phase is the two phases where some of the example models above are created, both under business modeling and requirements. For the Inception phase of RUP, the idea is to create the software application without writing any source code. This phase is concerned with writing text and creating models that gives the developers a detailed specification on how the program should be implemented. In the Elaboration phase a prototype might be implemented to show the customer a possible implementation, but this phase also consist of creating and modifying an extensive amount text and models that specifies analysis and design choices. The Elaboration phase focus on designing the architecture for the software application. The goal for these two phases is to define a solid foundation of the application before starting with the implementation and testing. In the Construction phase the developers should know exactly how the application should be implemented by referring to documents and models created in earlier phases. RUP is only one example of how a software development process could be applied to a project. Agile development processes has become popular the last couple of years, where processes like Scrum and Extreme Programming (XP) has been integrated in software development teams all over the world. Both Scrum and XP thrives to focus more on the implementation and on delivering high quality code than creating documents and models. But models will always be a tool for developers, also in agile development processes, when some aspects of a system needs to be explained. Because to explain parts of an implementation with a model will help to make the explanation less complex and more abstract.

![Iterative Development Cycle of Rational Unified Process](image)

**Figure 2.1: Iterative development cycle of Rational Unified Process.**

Now we have acknowledged some development processes that are commonly used in the industry for creating software applications. Model Driven Engineering is a software development methodology which focuses on creating and exploiting models. And by using these models, MDE aims at improving productivity and quality in software development. This is achieved by not only to use models as documentation, but instead to use models as the major artifact in a software development cycle. The idea is to use models at different levels of abstraction and apply model transformations to automate the implementation of these models. This will raise the level of abstraction in program and problem specification. We can divide these models into two main model classes, namely development models and runtime models. Development models is used as an abstraction above code level. These models could represent software requirements, work flow, architecture and software implementation. These development models are most typically used in software development process that we described above as a supplement...
in developing an application. Runtime models represents executable systems of a software application. Example of such executable systems could be database operations or computations of data. There has been an increase in MDE researchers that explore how runtime models can be used to support dynamic adaptation of systems for a software application[7]. The idea for MDE is to be able to specify these development models as runtime models and evolve software applications with the use of runtime models and development models as major artifacts of a development process.

A typical Model Driven Software Engineering (MDSE) approach is to obtain the running software application through model transformations that produce a more and more detailed version of the application until an executable version is created. We reach this level of automation by applying model transformations to models at higher levels of abstraction and producing models that contains a more and more detailed description of the software. This highlights one main advantage of a model driven approach, and that is to bridge the communication gap between requirements/analysis and implementation[8]. For a traditional development process today there is a gap in communication between software developers and customers. Because a customer is usually not an expert in designing and implementing a software application. A customer can provide a set of requirements for a software application and take part in analysing these requirements to make sure that the development team shares the customers thought of the program. The requirements and analysis can be specified down to every detail, however a software application might experience different design choices that leads to a different implementation of the application compared what a business needs. If the visions of MDE is adopted to a software development process then this could help to narrow the gap in communication between developers and stakeholders. Because now we can apply model transformation that changes input models to target models that represents the design of a software application. From these design models we can then generate implementation code through the use of model transformations. We will describe model transformations and their purpose in model driven engineering in more depths in chapter 3. To use models at each level of abstraction is less complex than implementation code. This represents another benefit of adopting MDSE into the development process. Because models captures and organize the understanding of a system that results in a more clear discussions among team members and new team members. One approach that introduces modeling at different level of abstraction for including MDSE in a software development process is the Model Driven Architecture.

2.1.1 Model Driven Architecture

Model Driven Architecture (MDA) is an industry architecture developed by the Object Management Group (OMG) and address an application development cycle. MDA is a proposal for applying the practices of MDE to a system development. This architecture is a good example to use when we are discussing concepts of MDE, because of its similarity to a traditional software development process. Since it has support for standard phases in a software development process such as analysis, design and implementation. Many organizations have adopted MDA as a reference framework to include the concepts of MDE. One reason for this is the importance of OMG in for the software industry. MDA is build around many concepts that OMG has released, such as the OMG specifications the Unified Modeling Language (UML) and the Meta Object Facility(MOF).
Chapter 2. Background

Figure 2.2 gives a representation of the development process that the Model Driven Architecture provides and a traditional development process. Both of the approaches have similar starting phases, where a customer presents a list of requirements for a software application. The process to create implementation code from the requirements is where a MDE approach to software development is different. Because for MDA the idea is to use models instead of text and diagrams for the analysis and design phase. For a traditional development process these phases usually consist of creating diagrams that describes parts of the application. In MDA these diagrams or models are the main artifact for the corresponding phases, instead of just a reference for developers to use when implementing code. The architecture then generates implementation code based on these models. A traditional software development process would have iterations for the implementation and testing to make sure that the application meets the demands of the customer. This process is continued for every iteration, where developers continually use the text and diagrams that was created earlier in the process. The idea for an MDA development process is to provide automation between models created at each development phase. Instead of going back to the code and to corrections and modifications on the application a model driven software development process goes back to analysing the problem and modify the models accordingly. With the power of automatically changing models from one phase to another and generate implementation code from the models at the last level of abstraction.

Figure 2.3 provides a representation of the models at the different layer of abstractions that is part of the Model Driven Architecture.

**Computation-Independent Model (CIM)** is the most abstract level of modeling and is often referred to as a business model or domain model. The model does not contain any computational implications to how the software application should behave, but express exactly what the final application should do. This model remains independent to how a system will be or currently is implemented and represents the requirements and purpose
of the system. A Computation-Independent Model is often described by using a natural language to define the requirements for a software application.

**Platform-Independent Model (PIM)** is the level of abstraction that describes the behavior and structure of a software application. This model is platform independent, and that means that a implementation platform is not specified. This means that the technological platform used to implement the software application is not defined. A Platform-Independent Model will only address tasks that a software application can perform. These tasks are part of the context of the business model at the top level of abstraction.

**Platform-Specific Model (PSM)** is the level of abstraction that contains all required information for the behavior and structure of a software application that is linked to a specific technological platform. These specific platform technologies can be a specific programming language like a general purpose programming language, a specific operation system or a specific database technology. The Platform-Specific Model contains all the information that is required for an actual implementation of the application.

In MDA, the core activity is the starting phase, which is the way analysis is conducted. Requirements are firstly defined and modeled as a CIM or a PIM. The CIM and PIM provides the solution for the requirements at a very high level of abstraction. At the computation independent level of abstraction we provide the requirements of a solution without thinking about the actual implementation of an application. A CIM could not only specify how an application should behave to different situations, but could also specify how the end users utilizes the application. For example the model could define the requirements for a web application that provides a collection of goods that the end users can purchase. These requirements could specify how an employee performs tasks when a new order arrives. For a solution to an application not all of these requirements
are necessary for the implementation. The meaning of MDA is that models created at CIM level provides the highest level of abstraction and therefore should be readable for everyone. In figure 2.3 model MDA suggest that new models are created accordingly from a set of mappings. Models that is provided at the platform independent abstraction is not concerned with technologies that should be used for the actual implementation. PSM is more concerned with describing what tasks an application should perform. But tasks that an employee should perform, like for example making a shipment ready for transportation is not defined in a PIM. A platform specific model specifies what implementation platform and a set of precise descriptions of the technical details of the corresponding implementation platform. Mapping a model to another model is essential for applying MDA to a development process. A mapping defines correspondences between elements of two different models and can be defined between all different models. These three models with mapping between them makes for excellent design choices to create an environment that specifies modeling languages.

### 2.2 Modeling Languages

A Modeling language is defined through three core concepts. Regardless if its either a Domain Specific Modeling Language (DSML) or a General Purpose Modeling Language (GPML). Figure 2.4 represents the three main ingredients for a modeling language.

![The three main ingredients of a modeling language.](image)

A modeling language has an abstract and a concrete syntax. The abstract syntax describes the structure of the modeling language and how modeling elements can be combined together. The concrete syntax on the other hand describes a specific representation of the abstract syntax, and can be either be a graphical or textual representation. The semantics of a modeling language describes the meaning of these modeling elements and the different ways to combine them for the abstract syntax and indirectly the concrete syntax. We mentioned DSML and GPML, where these two modeling languages represents one of the main classification of modeling languages. A modeling language can either be classified as a domain specific or a general purpose language. DSMLs are modeling languages that are designed for a specific domain or a concept. While GPMLs are modeling languages that is applicable for several different domains. A general purpose language lacks features that are special for a particular domain. This is one of the strengths for DSLs that is created especially for a certain domain, and therefore provide more details to a specific domain compared to a general purpose language. The Unified Modeling Language\[1, 9\] (UML) is an example of a standardized general-purpose modeling language that was accepted in 2000 by the International Organization for Standardization (ISO) as an industry standard for modeling software systems. UML
was initially developed by Grady Booch, Ivar Jacobsen and James Rumbaugh at Rational Software in the 1990s. It was later adopted by the Object Management Group in 1997 and has since this day been continuously developed by the organisation. UML is often called a general purpose language because it is often referred to as a suite of languages, since it provides developers and designers with the possibility to specify applications through several different modeling languages, or diagram types that UML often is associated with. However, in the book, “Model-Driven Software Engineering in Practice” published by Marco Brambilla, Jordi Cabot and Manuel Wimmer in 2012, they state the following. *If we think to the general modeling problem, we can see UML as a DSL tailored to the specification of (mainly object-oriented) software systems*. This means that to decide whether UML is a DSL or a GPL is not a binary choice. But we mostly see UML as a general purpose modeling language, since it offers a wide variety of modeling languages that designers and developers can use to specify system abstractions. Whether a modeling language is classified as a general purpose or a domain specific modeling language it requires that it is described by an abstract syntax. Both the abstract syntax and the concrete syntax of a modeling language is represented as models. Therefore the specification of the abstract syntax is often referred to as a meta-model.

### 2.2.1 Meta-modeling

Models are a major artifact in the concept of model driven engineering (MDE). It is essential to look at every model as instances of some more abstract model. And therefore we can define a meta-model as yet another abstraction that highlights properties of an instance model. Meta-modeling represents a vital part of MDE and constitutes the definition of a modeling language. A meta-model defines the abstract syntax and provides a description of a modeling language. Another popular definition for describing a meta-modeling is that it is a “model of models”. This definition is both unhelpful and incorrect according to Steve Cook and Stuart Kent in their paper published in 2008. They think that a better definition for a meta-model is that “it is a model of the concepts expressed by a modeling language.” The exact definition of a meta-model is highly debated amongst MDE researchers.

![Figure 2.5: A simple example of a model and its meta-model.](image-url)
Figure 2.5 shows a simple example of an instance model and its corresponding metamodel. This model has two classes, Student and Course, and a bidirectional association, take course and has students, that relate these two classes. The model is specified by a meta-model that consists of two meta-classes Class and Association and an association between them. Both Student and Course are an instance of the meta-class Class, while the association between Student and Course are instance of the meta-class Association. The modeling language that describes this model corresponds to the Unified Modelling Language.

Meta-Object Facility

The Meta-Object Facility[13] (MOF) is an Object Management Group standard for model driven engineering. The Object Management Group was in need of a architecture to define the UML. Therefore the Meta-Object Facility has its origin from UML. Through this process of finding a common platform for UML, OMG designed a four layered architecture that provides a semi-formal approach to creating meta-models. MOF became a language for defining abstract syntax for modeling languages.

![Figure 2.6: Example of Meta Object Facility and its four layers.](image)

Figure 2.6 gives a impression of the four layers that are available in the Meta-Object Facility. At the top level, M3 there is a meta-meta-model called MOF. This meta-meta-model is meant to both describe it self and conform to itself. MOF is then used to describe meta-models at the M2 level. The UML meta-model is an example of such a meta-model. The idea is that these meta-models are specified by some meta-modeling language. Models at the M2 layer represents the abstract syntax for models created in the M1 layer. This layer represents models that are created by some modeling language,
like for example UML. Finally at the $M_0$ we have an instance model of a real world object. If we refer to our simple example concerning a model and its corresponding meta-model in figure 2.5. From this example we can create a real world object of that model, “Petter Barvik” takes a course in Model Transformations. MOF provides meta-modeling architecture where every modeling element on every layer corresponds to some modeling element of one layer higher. One could say that MOF is a Domain Specific Language (DSL) to create meta-models.

2.2.2 Constraints

Constraints impose conditions that modeling elements must satisfy and helps to define the semantics of a domain specific language. A constraints can be compared to a Boolean condition. Boolean conditions are either true or false, while constraints are either satisfied or not satisfied. Including constraints to modeling elements in the abstract syntax specifies how modeling elements are presented in an instance model. Modeling elements that are included in the abstract syntax can have constraints defined on objects, classes, attributes, links, associations, etc. A constraint is a restriction on how these elements should behave. Constraints on elements such as those above can be expressed with a natural language or by a formal language, such as the Object Constraint Language (OCL). The Object Constraint Language (OCL) is a declarative programming language for describing constraints that applies to UML models. Before UML became an adopted standard of the Object Management Group (OMG), OCL was an extension language to UML. Now OCL can be used with any Meta-Object Facility (MOF) meta-model, including UML. A software developer can in combination with UML and OCL define the semantics for a modeling language.

The difference between object and classes needs to be specified. A class is often a meta element for an object. This means that a class could be part of a model that describes an object element, and therefore an object element is typed by class element. Figure 2.5 describes the two object elements Student and Course that are an instance of the meta-element Class.

![Figure 2.7: Example of a simple model with attached and structural constraints.](image)

These restrictions on model elements can either be a structural constraint or an attached constraint. These structural constraints are defined in the structure of the models. In figure 2.7 we have extended the model we introduced in figure 2.5 with some modeling elements. We have created an association that specifies that a student can date other students. In this model we can see that the model has three multiplicity constraints that are part of the models structure. A multiplicity constraint for an association restricts
the number of objects that are related to a given object. From the association constraint on this model we can see that a student requires to take at least one course and up to a maximum of six courses. The models restricts a student to not participate in any courses. The second structural constraint requires a course to have at least one student for this course to be part of a semester, and the course can have an arbitrary maximum number of students participating this course. The association dates, between two students for this model has an attached constraint, that is specified in the declarative language OCL. The general form of an attached constraint has a context, in this case a Student, that specifies what object the constraint includes. The is a constraint name followed by a Boolean expression. The attached constraint has a name “Irreflexive” followed by a Boolean OCL expression that explicitly refers to itself. This constraint specifies that a student is unable to date her or him self. Constraints has a vital part in model driven engineering to measure the quality and precision of a model. A model without constraints does not work in practice. In The Object Constraint Language: Getting Your Models Ready for MDA[15], Jos Warmer and Anneke Kleppe states that a model without constraints would be severely underspecified. Constraints expressions written in OCL are unambiguous and results in a more precise and detailed model. If we were to remove both the structural and attached constraints from figure 2.7 then the model is less informative. There is no understanding on how the objects are related to one another.

2.3 Language Workbenches

Language workbenches are tools that lets user specify their own Domain Specific Language (DSL) and include editing tools for the newly created language. A workbench should consist of Integrated Development Environment (IDE) that lets users create their own DSMLs. Figure 2.8 is provided in the paper, “DPF Workbench: a multi-level language workbench for MDE”, that was published by Yngve Lamo, Xiaoliang Wang, Florian Mantz, yvind Bech, Anders Sandven and Adrian Rutle in 2013. The figure presents the intended use of language workbenches and consist of two phases. The first handles the definition of a new DSML and the creation of tool support such as code generation, editors, model transformations, etc. A language workbench is created by a domain expert in collaboration with an experienced developer. The latter describes the actual usage of this newly created workbench, where developers can utilize the DSML environment to create models, generate implementation code, etc. Language workbenches are a very young field in computer science, and there are many existing solutions that is open for the public to use. These concepts have the potential to change the face of programming as we know it[17], but the concepts of workbenches are still fresh to computer science.
The concepts behind a language workbench is that the tool does not just provide the users with an IDE to create DSLs, but also generates a new IDE where this newly created DSL can be edited. In addition to an IDE that provides creation and editing of a newly created language a workbench should define support for code generation, model transformation, model versioning, etc[18]. Figure 2.9 shows the different components of a language workbench.

- The abstract representation for the language.
- One or more editing environments for the language.
- Defining the semantics behavior of the language.

2.3.1 EMF

Eclipse Modeling Framework is originally based on Meta Object Facility (MOF) provided by the Object Management Group (OMG). In 2003 EMF designers contributed
to designing the MOF 2.0 version of the standard that was named Essential EMOF (EMOF). EMF provides the meta-model Ecore that is aligned to EMOF and is a modeling language to build modeling languages. Ecore is essentially a simplified version of class modeling in UML.

Figure 2.10: A graphical representation of an Ecore model.

Figure 2.10 represents an Ecore model that is created from a graphical editor. This Ecore model conforms to the Ecore meta-model and is the core language for EMF. The framework provides a two layered approach to meta-modeling where the user can create a DSL based on the Ecore meta-model. Based on the DSL the framework provides code generation facilities. Amongst generating java implementation for the model the framework also provides code generation for an editor that is based on the DSL. This editor can be used to create instances of the defined DSL.

### 2.4 Diagram Predicate Framework

Diagram Predicate Framework[12, 18, 19] (DPF) is an ongoing research project that was first initiated by Bergen University Collage and the University of Bergen in Norway 2006. With features likes meta-modeling, model transformation and model management, DPF aims at formalising concepts of model-driven engineering. DPF is based on category theory and graph transformations and is an extension of the Generalised Sketches[20] formalism that was initially developed by Zinovy Diskin.

In October 2002 Dominique Duval published a paper where he specified that a specification can be considered as a directed graph with additional structure in the same way that a theory can be considered as a category with additional structures[21]. Generalised Sketches by Zinovy Diskin utilize the concept of sketches. A sketch, first introduced by Ehresman in 1966, is a directed graph that provides additional properties, such as colimit, limit and constraints. DPF utilize this concept through an diagrammatic approach
Chapter 2. Background

to meta-modeling and to facilitate the concepts of MDE. The framework provides the possibility to define an unlimited layers of meta-modeling. In DPF models are represented as specifications.

- A specification $\mathcal{S} = (S, C^S: \Sigma)$ consist of an underlying graph $S$ and a set of atomic constraints $C^S$.
- Atomic constraints are specified by predicates from a predefined signature $\Sigma$.
- A signature $\Sigma = (\Pi, \alpha)$ consist of a collection of predicates.

A specification $\mathcal{S}$ has an underlying graph $S$ that contains modeling elements that defines the model structure of the specification. These modeling elements are always represented as a node and an arrow. However these nodes and arrows could be specified through several layers of meta-models or specifications. The specification $\mathcal{S}$ also consist of a set of constraints, these constraints will restrict the model structure of a new instance model of this specification. Figure 2.11 presents a specification $\mathcal{S}_2$, that is defined by an underlying specification $\mathcal{S}_3$ and describes a modeling language for some $\mathcal{S}_1$ specification. This specification includes two nodes Condition and Activity, two arrows ChoiceOut and Message and two sets of atomic constraints. The first constraint defines that a Condition element has to be connected to exactly one Activity element for this structure. The second constraints specifies for this graph structure that an Activity element cannot be associated with it self. These constraints examples are specified as a collection of predicates from a predefined signature $\Sigma$. The table in figure 2.11 represent some of the predicates from this collection. A predicate is represented by an unique symbol $\Pi$, a shape graph $\alpha$, a proposed visualisation and a semantic interpretation.

![Diagram Predicate Framework](image)

Figure 2.11: A specification $\mathcal{S}_2$ with some attached predicates.

An instance specification $\mathcal{S}_n$ that is initialised from a specification $\mathcal{S}_{n+1}$ defines a graph homomorphism between two underlying graphs. There is a graph homomorphism, $S_n \rightarrow S_{n+1}$, between the underlying graph $S_n$ of a specification $\mathcal{S}_n$ and the underlying graph $S_{n+1}$ of a specification $\mathcal{S}_{n+1}$[18]. The graph homomorphism $S_n \rightarrow S_{n+1}$ must satisfy a set of atomic constraints, $C^S$ from a specification $\mathcal{S}_{n+1}$. Figure 2.12 from Adrian Rutle’s dissertation, Diagram Predicate Framework A Formal Approach to MDE[12] that was published in 2010 represents an example of a specification that is defined by a modeling formalism.
Because in DPF a modeling language is represented as a modeling formalism. A modeling formalism in DPF is defined by a set of atomic constraints and a specification that has an underlying graph and a set of atomic constraints. For example figure 2.12 represents three levels of abstractions for defining a DSML. The specification $S_1$ that is defined at the first layer corresponds to the modeling formalism one layer higher. The modeling formalism consist of a specification $S_2$ that has an underlying graph $S_2$ and a set of predicates $Z_2$. Together with specification $S_2$ a set of predicates $Z_2$ can be defined together with the underlying graph $S_2$ to define a modeling formalism[12]. This defined modeling language, or modeling formalism provides the abstract syntax that can be used to create a specification or modeling formalism one abstraction layer lower. What is special with DPF is that a modeling formalism represents both the abstract syntax for a specification one abstraction layer lower and the concrete syntax for a specification one abstraction layer higher. The set of atomic constraints $Z_2$ provides the semantics while the specification $S_2$ provides the abstract syntax for defining a new specification $S_1$. Figure 2.13 explains the difference between OMG’s MOF on the left side and DPF’s multi layer meta-modeling hierarchy on the right side.
These two sides highlights the differences between DPF and modeling environments that expand MOF to create modeling languages. While MOF based modeling environments provides two abstraction layers, DPF on the other hand provides a possible unlimited abstraction layers users can interact with. The reason that MOF based modeling environments provides two layers to interact with is because the layers $M_2$ and $M_3$ are usually part of the environments internal infrastructure. For example in EMF users can create models that conforms to the Ecore meta-model. The only meta-model that users of DPF are unable to interact with located at the highest abstraction layer. A specification $S_{n+1}$ is specified by a modeling language that corresponds to a specification $S_{n+2}$. But the same specification $S_{n+1}$ also represents the abstract syntax for a specification $S_n$. These DPF models automatically generates a new graphical editor environment provided by the DPF Editor.

### 2.5 DPF Workbench

The DPF Workbench provides a modeling environment for DPF and consist of three main components. These are the “DPF Model Editor”, the “DPF Signature Editor” and the “DPF Code Generator”. The first two editors provides the modeling functionality for the DPF Workbench. “DPF Model Editor” is used to create and modify DPF specifications. The “DPF Signature Editor” is used as a supplement to the “DPF Model Editor”. It provides an editor to construct user defined predicate signatures. These signatures can then be used to define the semantics of a DPF specification in the “DPF Model Editor” if the predefined predicates that DPF provides does not suffice. Figure 2.14 that is provided in the article, “DPF Workbench: a multi-level language workbench for MDE”[18], explains how the “DPF Signature Editor”, the “DPF Model
Chapter 2. Background

Editor” and a DPF Model is related to each other in the DPF Workbench over different abstraction layers. The “DPF Code Generator” provides the users with a code generation environment for DPF specifications.

![Diagram of a multi-layer meta-modeling hierarchy](image)

**Figure 2.14:** Generated DPF Editors in a multi-layer meta-modeling hierarchy.

DPF Model Editor

The DPF Model Editor is an extension of the Diagram Predicate Framework that provides an intuitive approach to creating modeling languages and have been created using several different technologies. In 2011 Øyvind Bech published his master thesis[22] where he designed the implementation of the DPF Model Editor that is based on the Eclipse Modeling Framework technology. This first version of the DPF Model Editor has seen several iterations and provides support for creating domain specific modeling languages. Figure 2.14 explains that a new instance of the DPF Model Editor is generated for each new model that is created. This means that every DPF specification has a corresponding editor that provides graphical editing properties to change the models. For each generated editor we can create a new DSL one abstraction layer lower that generates a new editor that correspond to this DSL.
Chapter 3

Model Transformation

Transformations are a fundamental aspect in computer science and software engineering. Whenever a computer starts up, transformation of computer systems and computer programs happens frequently. Take a compiler for instance, it plays a vital part of a computer's internal infrastructure. A compiler is a computer program that translates source code written in a high-level programming language into a lower level language, such as an assembly language or machine code. This means that a computer program written in a general-purpose programming language, such as Java or C++, would be useless without a compiler, since the computer's central processing unit (CPU) depends on machine code to be able to execute a set of instructions. But also computation of primitive data values and performing operations on data structures such as lists and arrays can also be viewed as data transformations. When a programming language provides a way to type these data values or data structures, then a compiler or interpreter can apply operations to the data accordingly to the type. But when we mention data representing software artifacts such as a data schema, programs or models, then transformation approaches

3.1 Basic concepts of model transformation

The very basic concept of a model transformation on the highest level of abstraction is to translate one model to another model. This model translation can either be achieved through an endogenous or an exogenous model transformation. For an endogenous model transformation we take a source model expressed in a modeling language and produce a target model expressed in the same modeling language. While an exogenous model transformation translates a source model expressed in one modeling language into a target model expressed in another modeling language. It is essential that these models remain consistent, and therefore both the source and target model have to conform to their corresponding meta-models.
Figure 3.1: The basic concepts behind a model transformation.

Figure 3.1 represents the basic concepts of a model transformation. The two concepts, transformation language and transformation engine are provided by some model transformation environment. The main idea behind changing two models are to read a source model and write a target model. The transformation engine executes a set of guidelines provided by a transformation language that express how the target model is constructed. These guidelines is created from meta-data that are defined in the source and target meta-model to create an executable environment for the transformation engine. Where the transformation language refers to both the source and target meta-model when specifying these guidelines. The transformation language specifies how a translation between two models should be applied through the abstract syntax that the meta-models provides. Note that the concrete syntax for a domain specific modeling language could be represented either graphically or textually. Traditionally when we use the concept model, we consider a graphical syntax, with nodes and vertexes that are connected with arrows and edges. However a model can also have a textual representation and therefore we often say that a model transformation can produce two different kind of target models. At the highest level of abstraction these two different target models can either be produced by a Model to Text (M2T) transformation or a Model to Model (M2M) transformation. A Model to Text transformation takes a source model and produce sequences of strings as a target model. The other approach, Model to Model transformation takes a source model as an input model and produce a target model. The main distinction between the two categories is that a M2M transformation produce an instance model that conforms to some meta-model while an M2T produces implementation code as its target model. We can expand the knowledge we have so far with model transformations that these endogenous and exogenous can produce a target model over different layers of abstractions.

3.1.1 Layer of Abstractions

In the beginning of 2006 Tom Mens and Pieter Van Gorp published a paper[23] that explains different aspects of model transformations. One aspect of model transformation they address is the direction through abstraction layers for endogenous and exogenous model transformations. In their paper they state that the “dimensions horizontal versus vertical and endogenous versus exogenous are truly orthogonal”[23]. Horizontal and vertical model transformation are two categorizes that describes transformations over different layers of abstraction. In MDE a layer of abstraction represents models that are specified by models from a higher layer of abstraction. For example a class diagram that is specified by the UML model. Modeling elements that are defined for the class diagram
Chapter 3. Model Transformation

is represented on one level of abstraction while modeling elements that are defined by the UML model is represented one abstraction level higher. This looks familiar concerning meta-modeling. An instance model of a meta-model is located on an abstraction layer lower than the abstract syntax. Consider table 3.1 that was published in paper\cite{23}. The table describes some examples of different model transformations over layers of abstractions.

<table>
<thead>
<tr>
<th>Transformation Type</th>
<th>Horizontal Transformation</th>
<th>Vertical Transformation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Endogenous Transformation</td>
<td>Refactoring</td>
<td>Formal refinement</td>
</tr>
<tr>
<td>Exogenous Transformation</td>
<td>Language migration</td>
<td>Code generation</td>
</tr>
</tbody>
</table>

Table 3.1: Example model transformations.

Previously in this section we discussed that changing a model to another model can either be applied by an exogenous or an endogenous model transformation. But when we consider these two types of model transformation we can also express that model transformations are vertically or horizontally translated amongst abstraction layers. For a vertical model transformation a target model is translated according to models that are specified on a higher abstraction level, while a horizontal model transformation produces a target model that correspond to a different abstraction layered hierarchy. The table above express that that we can have for example endogenous model transformations that provides refactoring or formal refinement of models. These two example transformations are applied differently concerning abstraction layers. Refactoring is an example of a horizontal model transformation that applies changes to a model expressed in some modeling language, and since this is an endogenous model transformation we can safely assume that the abstraction level is the same before and after the transformation is applied. A specific model refactoring example is the Pull Up Attribute\cite{24} that moves a common attribute from a subclass of a given class to this class. Language migration is another example of a horizontal model transformation, and is an exogenous model transformation that produces a model expressed in a different modeling language compared to the source model. A classical example of a language migration is to translate a class diagram to a relation database model. This example has become more or less a benchmark for model transformation tools and provides a transformation for a modeling language that is specified through a abstraction layer hierarchy to a modeling language that is specified through another abstraction layer hierarchy. The reason for mentioning that an abstraction layer is part of a hierarchy is because there exist solutions for creating a domain specific modeling languages over an arbitrary layers of abstractions, such as the Diagram Predicate Framework\cite{18} (DPF), metaDepth\cite{25} or Visual Modeling and Transformation System\cite{26} (VMTS). Comparing these with the Eclipse Modeling Framework (EMF), that provides a two layered approach to specifying a DSML, we can say that exogenous model transformations are applied to a two layered abstraction hierarchy. EMF creates a DSML based on the Meta Object Facility and therefore provides the user the possibility to define a DSML as a meta-model and create an instance model of this DSML meta-model. While the three other tools mentioned above provides an n-layered meta-modeling environment to specifying DSMLs. This means that a source DSL might only be described in one meta-model while a target DSML might have been specified through several layers of meta-modeling. Regardless of how many abstraction layers a DMSL is defined over for a source and a target model, the model transformation is provided horizontally. Code generation is an example of a model transformation that vertically translates through layers of abstraction and is usually the final model that
Chapter 3. Model Transformation

is produced in a model driven development cycle. Code generation is a Model to Text transformation that translates a source model that is described by a DSL and produce a target model that usually is described by a general purpose programming language, such as Java or C++. Figure 3.2 represents both a vertical model transformation and a horizontal model transformation. We can see that the vertical model transformation example represents a small portion of the MDA approach to software development, where implementation code is generated from a collection of platform specific models. The horizontal model transformation example provides a different example to model transformations, that is merging models into another model and is convenient for synchronizing models.

Figure 3.2: Vertical and horizontal model transformations.

The other provided example is a vertical model transformation that presents the last example of an endogenous model transformation, and that is refinement of a model. The three model types that MDA provides can be viewed as a endogenous model transformation that provides a model that is gradually refined into executable implementation code, by going through refinement steps that add more details to the model. For example when mapping a platform-independent model to a platform-specific model, like we discussed in section 2.1.1.

3.2 Model Transformations in MDE

Model transformations are in the center of Model Driven Engineering. The vision for MDE is to increase automation of models between level of abstractions. This vision is achieved through the use of model transformations. Either if it is to use a model to text approach to generate source code, or by transforming a model to another model where both models concrete syntax are specified by an abstract syntax that a metamodel provides. A model driven approach to software development thrives to keep a high level of abstraction for as long as possible through translating these models. And therefore model transformations are essential to be able to deploy model driven engineering in a software development process. The principles behind OMG’s Model Driven Architecture utilize the concepts behind model transformation to a full extend. Figure 3.3 gives a representation of how MDA wishes to facilitate the use of models and model transformations in a software development. The figure was published in Kim

We can see the different level of abstractions that the architecture provides and how to translate between abstractions. Remember what we discussed in section 2.1.1 that the architecture represents a software design approach for developing software applications. Where it expands the requirements of a software application into models and at the last level of abstraction the architecture provides implementation code for the application. The code that is generated most likely requires some additional work by developers, but a major part of the implementation code is generated through the use of models. Figure 3.3 explains that a set of transformations are required for a model to fuse to another model, or said differently, for a model to be integrated into another model. These transformation rules, that specifies how a model from a high level of abstraction is translated to a model on a lower level of abstraction, provides a development process that produce implementation code through automatically generating models on different levels of abstraction. Models and model transformations are equally important for MDE to be applied in a software development process. Without model transformations models would only represent an abstraction of a system. This means by utilizing model transformations in a software development cycle, models can evolve into executable implementation code by translating through different level of abstractions.

3.3 Existing Environments

There are a wide variety of existing model transformation environments and tools available. Some have experienced extensive testing through several iterations and some are relatively fresh to the MDE community. This section shortly describes some of these model transformation environments and how these environments approach translation of models. Because there are several different approaches to model transformations and
Chapter 3. Model Transformation

for the purpose of this thesis we will only address approaches that indicates model to model transformations.

OMG provides a standard that includes three such model to model transformation approaches. In 2002 OMG issued a request for proposal regarding Query/View/Transformation (QVT)\cite{28} where they sought a standard that was compatible with other OMG specifications such as MOF, UML, OCL, etc. This later lead to the release of Meta Object Facility (MOF) 2.0 Query/View/Transformation Specification in April 2008. The standard specifies the three model transformation languages or approaches to model transformation,

- QVT Operational is an imperative language that support implementation of unidirectional transformations.
- QVT Relations is a declarative language that supports implementation for both unidirectional and bidirectional model transformations.
- QVT Core is also a declarative language that is meant to act as the target of transformations from QVT Relations.

A unidirectional model transformation has only one mode of execution: that is, it always takes the same type of input and produces the same type of output. For a bidirectional model transformation, the same type of model can sometimes be input and other times be output\cite{29}. A model transformation in any of these three languages can itself be regarded as a model that conforms to a corresponding meta-model that is specified in the QVT standard. Note that an model transformation implementation based on any of these three languages requires source and target models that conforms to a MOF 2.0 meta-model. Since the release of the standard there has been several implementations of these three languages. The Eclipse Foundation have contributed with implementations of the QVT standard in the MMT project. The Model to Model Transformation (MMT) project hosts Model to Model Transformation languages. These transformations are executed by transformation engines that are written into the Eclipse Modeling infrastructure. MMT is a sub project of the top level Eclipse Modeling Project\cite{30}. ATLAS Transformation Language (ATL)\cite{31} is developed on top of the Eclipse platform and is one of three model transformation environments provided by the Model to Model Transformation (MMT) project\cite{32}. ATL is often referred to as a QVT Like implementation of the QVT standard. ATL is an hybrid approach to model transformations that implements techniques based on the three QVT languages. Another model transformation environment provided by the MMT is QVTo\cite{33} and is based on the QVT Operational model transformation language.

Model transformation environments like Visual Automated Model Transformations\cite{34} (VIATRA), Henshin\cite{24}, Graph Rewriting and Transformation Language\cite{35} (GReAT), The Attributed Graph Grammar System\cite{36} (AGG) and A Tool for Multi-formalism and Meta-Modelling\cite{37} (AToM³) are approaches that is based on category theory’s theoretical work on graph transformations. And model transformations that is based on the concepts of graph transformations have a LHS and a RHS graph pattern. The LHS provides a graph structure that is used to locate matching graph structures in a source model while the graph structure included in the RHS is meant to replace a matching graph structure. We will explore the concepts of graph transformations in more depths in section 3.5. But first we will describe some design features of model transformation environments.
3.4 Classification of a model transformation

In March 2006 Krzysztof Czarnecki and Simon Helsen published a domain analysis that covered existing model transformation approaches[38]. A domain analysis represents information on software system that share a common set of features for a given domain[39, 40], in this case the domain is model transformations. In their paper they presents the result by using feature diagrams, that provides a terminology and representation of the design choices for existing model transformation approaches. These feature diagram does not only represent model to model transformation approaches, but also consider the design choices for model to text transformation approaches. For the purpose of this thesis we will only address the model to model approaches in Czarnecki and Helsen’s survey on model transformations. However it is important to address that at top level, we can divide model transformations into to categories, namely model to text and model to model transformations like we discussed in earlier sections. We consider three feature diagrams that Czarnecki and Helsen produced in their report[38]. These diagrams are provided in figure 3.4, 3.5 and 3.6. This section is based on the ideas and results from Czarnecki and Helsen’s report and A Taxonomy of Model Transformation[23] that was published by Tom Mens and Pieter Van Gorp in 2006.

Figure 3.4: A domain analysis of model transformations[38].

Figure 3.4 shows the feature diagram at top level of a model transformation, where a subnode represents design choices for a model transformation. These design choices of a model transformation can give a better understanding on the different parts that a model transformation provides. A model transformation environment needs to tackle these design choices that figure 3.4 refer to in some manner. However, not all of these design choices are mandatory. Above each subnode in these three feature diagrams there is a black filled circle and an empty circle. The empty circle explains that these design choices are optional, like for example Specification and Incrementality, while the others are mandatory features for a model transformation. The rest of this section we will try to find a better understanding of the concepts model transformations.


3.4.1 Specification

3.4.2 Transformation Rules

For a model transformation to be able to translate a model to another model it needs a set of guidelines on how to achieve this. Therefore a model transformation has a set of transformation rules that specifies how a target model is produced. A transformation rule usually defines two special patterns. One pattern represents a searching pattern while the other pattern represents the part that is produced. An obvious example of such rules are the rewrite rules, that provides a left hand side (LHS) and a right hand side (RHS) where both sides represents some user created patterns that are considered when a transformation engine applies a corresponding transformation rule. But a function that implements some transformation steps can also be seen as a transformation rule. Regardless if the concrete syntax is either textual or graphical, the users have to specify a pattern that is used to locate matches and a pattern that is used to replace these matches with a result.

Domain

A transformation rule is specified by certain domains. These domains are responsible of accessing either the source or target model for each corresponding rule. A domain represents both the part that is used to find matching patterns in a source model and the part that produces a target model. For example for a classic rewriting rule we would have one domain for the LHS and one domain for the RHS of the rule.

Figure 3.6 gives a representation of what a domain contains. A domain is provided with a domain language. The domain language represents how we can structure the domains. In the context of model transformation tools that translates models that utilize the Model Driven Architecture this domain language would have form of a meta-model expressed in the Meta Object Facility. The domain language express what language we use to define the abstract syntax for both the source and target model. Static mode determines if a domain represents a searching part, a create target part, or as both.

Figure 3.5: Features for transformation rules.

Figure 3.6: Features for a domain.
Chapter 3. Model Transformation

The classic rewrite rules has a source domain that represents the LHS and a target domain that represents the RHS. Transformation rules that can be applied in both directions assumes all domains to be both a source and a target domain. **Dynamic mode restriction** concerns model transformation tools that provides rules in multiple directions, that means that the source and target model can act as both a source or target model depending on what direction a transformation occurs. For these rules a domain can be restricted to act as a source domain, and not as a target domain. A **body** determines the actual pattern for a domain. This pattern has a certain structure, where the pattern for example can represents graphs or strings. This pattern has a provided abstract or concrete syntax. The abstract syntax describes what modeling elements a certain pattern can contain while the concrete syntax determines if the modeling elements are textual or graphical. The body part of a domain can also contain logic that express computations and constraints on modeling elements. **Typing** determines the typing of the contents of a body. Patterns can either be untyped, syntactically typed or semantically typed. For syntactically typing modeling elements that are part of a pattern is associated with a meta-model element.

**Syntactic Separation**

Some approaches to model transformation includes syntactic separation of accessing models. These model transformation approaches clearly separates on what models a transformation rules operates. For example in rewrite rules the LHS operates on the source model while the RHS operates on the target model. Some model transformation approaches might not have any distinctive separation, like for example an model transformation implemented as a Java program.

**Multi-directionality**

Multi-directionality determines if model transformation approach provides transformation rules to be applied in different directions. This is convenient when synchronizing models over model transformations for example. Model transformation approaches that supports applying rules in both directions are usually defined over a domain that is both a source and a target.

**Application Conditions**

Transformation rules for some approaches supports application conditions. An application condition provides an extra property that specifies a filter for search patterns. Application conditions are handled differently amongst the model transformation approaches. Model transformation approaches that implements the QVT standard often use control flow statements like the when-clause or the if-then-statement that must be true in order for a transformation rule to be applied. Model transformations approaches that is based on category theory and graph transformations on the other hand specifies application conditions as graph structures that either requires or forbids this specific graph structure in a located matching graph structure.

**Intermediate Structures**

Some model transformation approaches requires intermediate structures when executing a set of transformation rules. These structures are usually only used as a supplement when applying a set of transformation rules. One example of an intermediate structure is a traceable link. These traceable links usually has a corresponding meta-model that is required to be included in a model transformation environment. Some approaches
to model transformation rely on this intermediate structure to be able to translate a model. An example to this is that this traceable link is created after a rule is applied to prevent this rule for locating the exact same match next time it is applied.

**Parameterization**

Parameterization allow for passing values to a transformation rule. For example we can pass data types, for example modeling elements to a transformation rule. We can then apply changes to a transformation rule with these provided parameters and at the same time use the same data types in other transformation rules.

**Reflection & Aspect**

Some model transformation environments allows for a reflective look up of target modeling elements for source modeling elements at runtime when target modeling elements are already transformed. For example a lazy rule in ATL allows for explicitly iterate over already transformed modeling elements and apply some reflective operation on the target modeling elements. Transformation rules that utilize an aspect-oriented extension are rules that can affect other rules when applied. Both of these categories can be used to express concern cross-cut other transformation rules. This means transformation rules that can directly affect other transformation rules.

### 3.4.3 Rule Application Control

This section can be divided into two sub categories, namely locating matches for a transformation rules and how these rules are be applied. Locating a matching pattern in a source model is rarely controlled by the users. The different model transformation languages utilizes optimized searching algorithms to locate these matches, where a rule has to be applied to a specific location in a source model. Usually there are more then one exact match for each rule, and therefore a transformation engine has to consider that there are several matches for a specific search pattern in a source model. There are multiple different search algorithms for locating these matches, but these search algorithms often have a common strategy to determining the application locations. The locate matches strategies could be applied deterministically or non-deterministically for example. It is important to differentiate between a strategy and a search algorithm. A strategy implies how an algorithm for locating matches is executed. An algorithm that is applied by a deterministic strategy, given a particular source model, will always produce the same output. For example for directed graphs a deterministic strategy could exploit some graph traversal algorithms, such as Breadth-first search\[41\] (BFS) or Depth-first\[41\] search (DFS). An algorithm that are executed with a non-deterministic strategy on the other hand can experience different behaviors on different runs. An example of a non-deterministic strategy is one-point application\[38\] and concurrent application. A one-point application applies a rule to a non-deterministically location in a source model. This means that a rule will search for matches at random locations within a given source scope. While a concurrent application applies a rule to all matching locations at the same time.

Before a matching pattern can be located in a source model a model transformation environment has to have a mechanism that schedules these transformation rules. Some model transformation tools provides the user with the possibility to explicitly decide when transformation rules are applied. The scheduling of transformation rules can be
Chapter 3. *Model Transformation*

3.4.4 Rule Organization

This feature represents how the rules are organized and if they are easy to reuse. The rules are usually represented as a collection of rules, where these rules could either be represented in some source code or by some tree based editor. Some model transformation approaches offer a modular approach to rule organizing. This means that the rules are contained in a module and are therefore easy to reuse. This gives the users the possibility to import these modules and use them in other modules. This modular approach to creating transformation rules can implement lazy rules, and lazy rules are transformation rules that can be integrated in other rules. These rules are highly reusable and can be used in any other module. In graph based model transformations rules are in most cases organized into a set of rules, where each rule is not available for other rules to use. This is because a transformation rule expressed in an algebraic approach to model transformation has the pattern and the replacement graph. And by adding a new rule with a new pattern graph and replacement graph will probably result in a transformation rule that search for matches that was not intended.

3.4.5 Source - Target Relationship

How can a model transformation environment distinguish if a model transformation is an endogenous or exogenous model transformation? This is achieved by specifying how a source model and target model are related to one another. These source and target models can relate to a meta-model for example. Both the source and target model could be described by the same modeling language. This specifies that a translation between source and target model are an endogenous model transformation. And as we
described in earlier in this section is that an endogenous model transformation translates one model written in one modeling language and produces a model written in the same modeling language. One aspect of this source-target relationship is that the source and target model are independent of each other. The model transformation environment is responsible to read and write these models, and to make sure that these models remain consistent. One could say that the target model are implicit depending on a source model, since a model transformation requires a source model to translate accordingly. The model transformation language creates transformation rules based on the corresponding meta-models that describes both the source and target model. And therefore administrate how these models relate to one another through these transformation rules. If the source and target models are written or modelled by using two different modeling languages, then we have an exogenous model transformation, and the relationship between the models should be adapted accordingly.

The source and target model can also in some cases be one and the same model, Model transformations that are applied one and the same model are called in-place model transformations. In AGG the source and target model are always the same model, and therefore AGG only supports in-place update of a model. The older versions of Atlas Transformation Language (ATL) requires that a new target model, that is separated from a source model is created when applying a model transformation. Creating a new model as a target model for a model transformation specifies that this is an out-place change to a model. However since January 2013 ATL support in-place transformations through a refining mode. Other approaches offers support for both in-place or out-place updates and lets the users specify how the models should be updated. These outplace model transformations could either be changes made to an existing model or by creating a new model. QVT Relations and Henshin is an example of approaches to these model transformations. Henshin does implicitly deliver an in-place model transformation environment, that allows for in-place update of models. But explicitly, when using the Henshin API, one could programmatically set up Henshin to do out-place changes to a model.

3.4.6 Directionality

This section describes that a model transformation environment can translate a model in multiple direction. We can distinguish the direction model transformations to either be unidirectional or multidirectional. An unidirectional model transformation has one source model that translates to a target model or updates a target model. What we then can do is change the source model and source meta-model with the target model and target meta-model. But this model transformation is not multidirectional, since we have to apply two model transformation to achieve this. A multidirectional model transformation can translate in different direction, regardless of source and target meta-model. This is especially convenient for model synchronising, where we can translate in multiple directions.

3.4.7 Tracing

Some model transformation environment has support for tracing of model elements. Tracing works like a fingerprint in a model transformation and has an unique link between elements. A traceable link between source and target elements is a link between
mapped elements when a model transformation is executed and provides information between the relationship between source element and its corresponding target elements. The traceable link is stored in memory for the duration it takes to execute a set of transformation rules. A traceable link is specified when creating the transformation rules and requires source and target elements. When there is a match in a transformation rule, a new traceable link is created between a matched source element and all corresponding target elements. These traceable links is very convenient when analysing and debugging a model transformation. Because now there is tracing on source and target elements on each time a transformation rule finds a match in the source model.

How traceable links are used across transformation tools varies. In Henshin, ATL and QVT these traceable links are handled automatically. For Henshin the user can use Henshin Trace model to create traceable links. The trace model consists of a single class Trace with a source and target reference. The user can then create this trace element together with the transformation rules to relate source and target models. ATL has an implicit tracing mechanism that specifies relationships between the source element and its corresponding target elements by using a native type called ASMTransientLink. For every time a transformation rule is matched to a source element, one ASMTransientLink is created. To this transient link the name of the transformation rule provided together with the source element and the target elements. These links are added to a collection that has all the transient links and stored internally for ATL. This means that the users of ATL cannot access these links after a model transformation has finished executing. However, as shown by Andrés Yie and Dennis Wagelaar, that gaining access to these ATL traces can be done explicitly by creating transformation rules that generates a tracing model based on the internal tracing information provided by ATL. In AGG traceable links are created as any other modeling element. Where the user can specify a node and two arrows between source and target meta-element in the type graph.

### 3.5 Graph based Approach to Model Transformations

One common approach to model transformations is by graph transformations, also referred to as graph rewriting. Graph rewriting can be implemented with an algebraic approach, which is based on Category Theory. Before we go into detail about graph transformation, we should quickly describe the concepts of Category Theory. Category theory can be used to formalize mathematical or software theory’s at a high level of abstraction. In 2006 Steve Awodey published a second edition of the book, Category Theory, where he stated, 

> “Just as group theory is the abstraction of the idea of a system of permutations of a set or symmetries of a geometric object, category theory arises from the idea of a system of functions among some objects.”
Category Theory can be used as a supplement to explain the theoretical aspects behind a problem or solution. A category consists of a collection of objects and functions. In figure 3.7 we have a collection of objects A, B, C and arrows \( f, g, g \circ f \). The figure describe that there is a connection between the two objects A and B. This connection indicates that there are some association between two objects. For this case this means that function \( f \) is defined in A and the values of this function are in B. When the objects represents graphs, then these connections between objects are often referred to as morphisms between graphs or graph morphisms. Morphisms are pair of maps which commute with source and target[8]. Figure 3.7 has three sets of graph morphisms, \( f : A \to B, g : B \to C \) and \( g \circ f : A \to C \). The last set of graph morphisms, \( g \circ f \) indicates that there is a composite function between A and C. This basically means that if C is a function \( g \) of B and B is a function \( f \) of A, then C is the result of a function between C and A.

For the purpose of this thesis the collection of objects represents graphs the arrows represents morphisms. A graph contains a collection of nodes and edges. A graph is undirected when there is no distinction between two nodes associated with an edge or it is a directed graph if an edge has a direction between two nodes. This means that each node is represented as a source and a target node for an edge. A directed graph L can be defined by \( L = \{ N_L, E_L, \text{source}_L, \text{target}_L \} \). \( N_L \) represents the collection of nodes and \( E_L \) represents the collection of edges that are included for the directed graph. The third and forth elements, \( \text{source}_L \) and \( \text{target}_L \), are functions that retrieves the source and target node for an edge. This collection of nodes and edges in a graph L can result in an exact match in another graph G. The morphism between these two graphs are called homomorphism.

**Graph Homomorphism**

When a graph that has a mapping of nodes and edges in another graph, then there is a graph homomorphism between these two graphs.

![Figure 3.8: Two sets of graph homomorphism of graph L in G and R in H](image-url)
Figure 3.8 has two graph homomorphisms \( L \xrightarrow{m_L} G \) and \( R \xrightarrow{m_R} H \). Now if we consider the first example, if there is to be a valid graph homomorphism between graph \( L \) and \( G \), then the collection of nodes and edges in \( L \) has to be mapped to nodes and edges in \( G \). If both graphs \( L \) and \( G \) are directed graphs we can safely assume that the definition of graph \( L \) in the last paragraph is also true for graph \( G = \{ N_G, E_G, \text{source}_G, \text{target}_G \} \).

For a graph homomorphism \( m_L \) from the graph \( L \) to the graph \( G \), \( L \xrightarrow{m_L} G \), there is a mapping \( m_L : N_L \rightarrow N_G \) from the set of nodes in graph \( L \) to the set of nodes in graph \( G \) and a mapping mapping \( m_L : E_L \rightarrow E_G \) from the set of edges in graph \( L \) to the set of edges in graph \( G \) that preserve both source and target nodes. This means that there is a mapping from a source node in \( G \) that is equal to a source node in \( L \) and a target node in \( G \) is equal to a target node in \( L \).

### 3.5.1 The Algebraic Approach

This approach are based on the concepts of composing graphs, modelled by pushouts of graphs and graph morphisms. This pushout approach comes in different variants, and we will look at two of these, namely the double-pushout (DPO) approach and the single pushout (SPO) approach[46, 47].

Historically, the first of the algebraic approaches to graph transformations, the double-pushout, was first introduced at the Technical University of Berlin in the early seventies by H. Ehrig, M. Pfender and H.J. Schneider[48]. They tried to generalize Chomsky grammars from strings to graphs. This allowed to define a graph rewriting step by the use of two gluing constructions. And by applying a graph rewriting step for the double-pushout approach is a pair of morphisms in the category of graphs where the arrows represents total graph morphisms, \( L \xleftarrow{K} R \). This is true for each application rule in a graph transformation for the double-pushout approach. Where the graph \( K \) represents the common part and the two morphisms \( L \xleftarrow{K} R \) use the algebraic construction, pushout to apply an application rule for a rewriting step. Hence the name double pushout and the use of two rewriting conditions.

### 3.5.2 Transformation Rules

For a transformation language to be able to execute graph transformations a set of application rules needs to be defined. Through these rules, a transformation interpreter can act accordingly. These rules can have many names, and are often referred to as productions or applications. For graph transformations, there can be an arbitrary number of rules. Its truly up to the users how they want to translate a language and how many rules that is needed to acquire this. Each rule consists of a left hand side (LHS) and a right hand side (RHS), also often referred to as pattern graph and replacement graph. The pattern graph represents a subgraph of the model that is going to be translated, namely the host graph. For these productions to execute, there is an application control mechanism that administrates the execution ordering of transformation rules.

### 3.5.3 Application Control

In graph transformation, there has to be a control mechanism that administrates these productions. These control mechanisms are also called transformation units. These
units controls the order that the transformation rules are executed. The most basic transformation unit is a rule itself which corresponds to a single application of that rule. But in most cases, a transformation unit will have to control several rule applications.

3.5.4 Execution of rules

The basic idea for graph transformation for both the double-pushout approach and the single pushout approach is to apply an application rule \( r: L \rightarrow R \). Where the rule represents a single rewriting step for graph transformations and \( L \) represents the left hand side of the rule and \( R \) represents the right hand side of the rule.

![Figure 3.9: The basic idea for graph transformation by applying a rule r.](image)

A production rule \( r, G \xrightarrow{m} G' \) indicates a direct derivation to a derived graph \( G' \). In figure 3.9, the graph \( G' \) is created by applying a single pushout for a transformation rule \( r \). If there is a match \( m \) of nodes and arrows for a subgraph \( L \) in a host graph \( G \), then this indicates a graph homomorphism, mapping elements from the subgraph to the host graph in such a way that the graphical structure in \( G \) is preserved. For each rule \( r \), there are some algebraic approaches to how we can achieve \( G' \). At this moment there are four approaches, the double-pushout approach (DPO) \[46\], the single-pushout approach (SPO) \[47\], the sesqui-pushout\[49\] and the pullback approach\[50\]. Where the two most common approaches used in graph transformation tools are the DPO and the SPO approach. There is one major aspect that separate these two approaches, and that is that the DPO approach has an application condition.

![Figure 3.10: Principles behind the double pushout approach.](image)

This application condition, named the gluing condition\[46\] consists of two parts. Namely the dangling condition and identification condition. From figure 3.10, the dangling condition requires that if the transformation rule \( p \) specifies the deletion of a node in \( G \), then it must also specify the deletion of all incoming and outgoing edges of this node in \( G \). By applying this condition, we can be sure that there are no dangling edges after deleting a node in \( G \). The identification condition requires that every element of \( G \) that
should be deleted by applying a transformation rule \( p \) is only present once in \( L \) for each transformation rule \( p \).

A single transformation rule \( p \) in the DPO approach is given by a pair of graph homomorphisms from a common graph \( C \). This common graph \( C \) is formed by taking elements that are present in both \( L \) (LHS) and \( R \) (LHS) of a transformation rule \( p \). The graph \( G' \) are created from the graph \( G \), by deleting all elements that is matched from the pattern graph \( L \), but none in \( C \). To avoid dangling edges, the gluing condition must be satisfied before deleting these elements. This is the first part (1) of the DPO approach, namely the deletion of elements. The second part (2) is insertion of elements. From here we create a graph \( H \) off all nodes and arrows from the replacement graph \( R \) that is not presented in the common graph \( C \). The DPO approach has the possibility to preserve elements from translating from the pattern graph \( L \) and the replacement graph \( R \) with the help of a common graph \( C \).

For the SPO approach on the other hand, deletion has priority over preservation. Figure 3.9 is a representation of the practices of the SPO approach. Where nodes that are present in the pattern graph \( L \) but not the replacement graph \( R \) are deleted. And the incoming and outgoing edges of the deleted nodes that are not present in the replacement graph \( R \) is deleted.

An application condition in graph transformation indicates an additional graph morphism that provides a transformation rules with extra properties. These applications can represent either a negative application condition or positive application condition. Both instances of application conditions are very similar since they indicates some additional information for a transformation rule. A negative application condition express requirements that a specific graph structure is forbidden to be part of the located matching pattern. On the contrary a positive application condition express that a specific graph structure is required for a located matching pattern to be a valid match for a transformation rule. Figure 3.11 represents a negative application condition\(^{51} \) (NAC).

\[
\begin{array}{c}
N \rightarrow n \rightarrow L \\
\downarrow n_G \downarrow m_L \\
G
\end{array}
\]

**Figure 3.11:** A Negative application condition.

The figure contains three graphs and three graphs morphisms. Graph \( L \) represents the LHS graph, graph \( G \) represents the graph that should be translated while graph \( N \) represents a negative application condition. A negative application condition specifies that a certain graph structure should not be included in the located match. A positive application condition on the other hand requires that a certain graph structure is part of a located matching graph pattern. Note that a negative and positive application condition is basically very similarly represented but implemented differently. For example the double pushout technique for graph transformations in figure 3.12.
Before the double pushout can be used, there has to be located a matching graph pattern in $G$. The graph $L$ will locate a matching pattern $m_L$ in $G$, then check if there exist an application condition $N$, whether or not this application condition requires or forbids a special graph structure there will be a graph morphism $n_G$ that states if a match is valid. This application condition filters the searching of graph patterns in $G$ each time a transformation rule is applied.
Chapter 4

Problem Specification

4.1 Problem Specification

The DPF Workbench already includes support for model transformations. However, the framework does not have support for transforming a model between different modeling languages. One of DPF’s strengths is that it is possible to formally define a Domain Specific Modeling Language by defining multiple levels of meta-models. What we want to do is to include tool support for the DPF Workbench that change a model from one meta-modeling hierarchy to another meta-modeling hierarchy regardless of the source models abstraction layer. This leads to the main question for this thesis.

• Can we include tool support for model to model transformations for the DPF Workbench that translates a model specified over a modeling hierarchy to a model specified over another modeling hierarchy?

The solution to this is not written in stone, and there are several approaches to how we can solve this specific problem. The tool requires some implementation but there are several existing approaches available that provides model transformations as we mentioned in section 3.3. DPF specifications are basically graphs, more specific, they are directed graphs. This means that a DPF specification consist of a set of nodes, arrows and two functions that preserves the source and target node. This makes a graph based approach to model transformations convenient, but we should also consider other approaches to model transformations.

• Can we integrate an existing model transformation environment with the Diagram Predicate Framework Workbench?

We want to introduce the DPF Workbench with tool support that includes model transformations. This has already been successfully introduced to the workbench environment in Anders Sandven’s master thesis. In his thesis he describe how he integrated a M2T transformation environment to the DPF Workbench. He integrated a model transformation environment, Xpand that provides a template based approach to Model2Text transformation. For this thesis however, we want to verify that we can successfully introduce a model transformation environment that supports translation between different
Chapter 4. Problem Specification

DSML’s. But first we have to find a applicable environment that can be integrated with the DPF Workbench. In section 4.2 we will explore three different model transformation tools that supports both exogenous and endogenous model transformations. One aspect of model transformations that is required to translate specifications in DPF is a set of transformation rules that describes how a target model is produced. This leads to a problem for the DPF, because a transformation rule requires modeling elements from some abstract syntax to specify a structural pattern that is used to locate matches in a source model.

- How can we include the abstract syntax of a modeling language that is specified to a corresponding linguistic meta-model and an corresponding ontological metamodel for a single transformation rule.

In 2007 Ralf Gitzel, Ingo Ott and Martin Schader published a paper where they amongst other subjects discuss the difference between Linguistic and Ontological meta-modeling. They provide a definition between the two, “Linguistic metamodeling uses a metamodel to describe a language syntax without a concrete real-world mapping. Ontological metamodeling uses metamodels to describe domain-specific hierarchies”\[54\]. As it is, the MOF 2.4.1 standard does not allow for more than a four layered meta-modeling. DPF has an Ecore specified meta-model that describes the language syntax and potentially unlimited layers of meta-models that describes the domain-specific hierarchy. Figure 4.1 gives a representation on how specifications are related and regardless of abstraction layer every specification $S_1...n$ conforms to one common meta-model.

This model is the linguistic meta-model that DPF provides to describe the abstract syntax for every single specification created by the DPF Model Editor. However, other than consisting of an underlying graph and a set of constraints, a DPF specification $S_n$ is also an instance of another specification $S_{n+1}$, and this is where it gets challenging. Because in the DPF Workbench a specification model $S_n$ is created as an instance from a specification model $S_{n+1}$. We can describe these specification models as ontological meta-models, since these models describes a domain specific modeling language through an arbitrary hierarchy of models. We have to find a way around this for our solution, because model transformation environments that utilize Ecore based models does not allow Ecore instance models to represent abstract syntax. This could serve a potential problem when integrating the model transformation environment with DPF. Modeling
elements that DPF provides are created as nodes and arrows from an Ecore based meta-model, but are at the same time created according to modeling elements one abstraction layer higher.

We will discuss how we address and approach these problems in the next chapter. But first we will look at some related work to model transformations. We have considered the tools, The Attributed Graph Grammar System\[^{36}\] (AGG) and Henshin\[^{24}\] that provides a graph based approach to model transformation. We have also worked with ATLAS Transformation Language\[^{55}\] (ATL), that provides a mixture of model transformation techniques and is therefore often referred to as a hybrid approach to model transformation. Through working with these three tools we can find a model transformation environment that is best suited to be integrated with the DPF Workbench.

### 4.2 Three different model transformation environments

These model transformation tools use different approaches to how model transformations are applied. We have looked at tools that implement classical rewriting steps that utilizes the theory behind graph transformations and tools that does this differently. For this survey we have tackled a specific exogenous model transformation example, that translates an instance model of UML’s activity diagram to an instance model of a Petri Nets\[^{56}\] model. The next two figures provides the abstract syntax of the two corresponding languages. These figures are represented as Ecore models, that is EMF’s interpretation of OMG’s MOF. It is convenient to represent these meta-model as Ecore models since both Henshin and ATL specify transformation rules according to such models. First we will quickly describe the corresponding abstract syntax for the two models before we consider the first model transformation tool.

![Figure 4.2: Abstract syntax of the source model for this test case.](image)

The abstract syntax for the source model has an arbitrary number of activities and next elements. Figure 4.2 describes that an activity element can have a name and a kind. The next element can have an inscription and provides the property to either begin or end activities. The collection of activities and next elements are provided by a specific activity diagram that.
The abstract syntax for the target model consist of places and transitions. A Petri net instance must have a place connected to a transition or the other way around, but a Petri net model can never have two of the same types connected. For this test case we defined two nodes that specify if a connection is between a place and a transition or a transition and a place. Note that these two meta-models are a simplified version of the abstract syntax. For this test case we are more concerned with how the different model transformation environments refers to the abstract syntax for the transformation rules. For each tool, if it is either a graphical editor or a textual editor, we discuss how to edit transformation rules, which is relevant for how we want to design a transformation tool for the DPF Workbench. We then consider how the different tools defines the abstract syntax for both the source and target model. Next we specify how transformation rules are created and if the tool provides any application control for these rules. We finish up by mentioning how the tool applies this model transformation. In section 4.3 we consider the model transformation environment that can be integrated and provides a viable model transformation technology that works with the DPF Workbench.

### 4.2.1 The Attributed Graph Grammar System

AGG is a general development environment for algebraic graph transformation systems that provide a graphical editor for creating and modifying graphs. The editor provides a graphical user-interface with several visual editors for applying the principles of graph transformations. AGG also provide an interpreter and a set of validation tools. The system is an ongoing research activity of the graph grammar group at the Technical University Berlin and started in 1997.

#### Graphical Editor

The graphical editor of AGG, represented in figure 4.4, has several functions to help the user to define model transformations. In the top left corner of the graphical user-interface is a tree based editor that provides a set of transformation rules, type graphs, and host graphs. The host graph represents both the source and target model in a model transformation, and the type graph represents the abstract syntax for the modeling languages. The source-target relationship of the host graph is one and the same, but we will discuss this in future sections, but for the purpose of this thesis we will refer to the host graph as the source graph.
Each transformation rule has two visual editors, representing the left (LHS) and the right hand side (RHS), or the pattern and the replacement graph. In the tree based editor it is also possible to attach application conditions to transformation rules. This is convenient if the user wants to specify constraints that restricts the pattern or replacement graph to be applied accordingly to the specific application condition.

Type graphs are described more in depths in the next section, but roughly said, the type graph defines modeling elements that can be used to create the source graph and is similar to how Ecore defines meta-models for EMF. The users can now create model instances that represents the concrete syntax of a specific modeling language. This representation of the abstract syntax are represented in a source and corresponds to its concurrent type graph.

The transformation rules can be extended with Java expressions. This means that the users can use Java primitives such as strings, integers or float numbers to form the pattern graph or the left hand side of the rule. However, the users can only bind attributes that are in a corresponding type graph.

Figure 4.4 also represents some node elements and association elements. These are meta elements that are initialized in the type graph and are used to model the source graph, the different transformation rules and application conditions. The node elements and association elements also describes the semantics of the type graph. Note that both the node elements and association elements in the figure has been scaled up for the purpose of this paper.
Defining Meta-models

Before the source graphs can be created, we have to specify the modeling language for the source model and the target model. In AGG both the source and the target meta-model are defined in one common type graph. The type graph represents the abstract syntax for both the source and target model. If we want to prepare an AGG graph for a model transformation, we create a type graph with references between source modeling elements and target modeling elements. AGG is unaware of the relationship between these modeling elements unless we explicitly initialize them. The relationship between source and target modeling elements in the abstract syntax has two major purposes for an exogenous model transformation. The relationship specifies how source modeling elements correspond to target modeling elements and determines upon execution of transformation rules that a matched pattern is only found once.

Figure 4.5: Type graph for activity diagram and Petri Net in AGG.

Figure 4.5 represents the type graph for our test case. The abstract syntax contains nodes and arrows that include a structural multiplicity constraint. The user defines nodes and arrows for each meta element for both the source and target model. This is achieved by using either the Edge Type Editor or Node Type Editor and are editors that correspond to either a node or an edge. The nodes and edges are given names and graphical properties such as colors or shapes. Nodes represents modeling elements from the two modeling languages while arrows represents the associations between these modeling elements. In the type graph we want to distinguish between associations and correspondences, and therefore we represent a correspondence between a source and target modeling element as a dashed arrow. The dashed arrow has the same properties as the association arrow between nodes, but the graphical representation is different. This makes the concrete syntax in the source graph easier to read when we are applying the transformation rules. In figure 4.5 we can see that a RefAct node is defined and is connected between the activity element and the transition element. The same initialisation is defined between the next element and the place element. This reference edge specifies that there is a correspondence between Activity and Transition element and between
Next and Place. For this type graphs there is a structural multiplicity constraint for the nodes and edges. This means that there can be an arbitrary, or a zero to many number of instances of these nodes and edges in the source graph.

Defining Transformation Rules

Now the type graph has been initialised and the instance graph of the source model has been created. But to be able to translate to a target model, we need to create a set of transformation rules. A transformation rule is defined with an unique name, an empty LHS graph and an empty RHS graph.

![Figure 4.6: Tree based editor for transformation rules.](image)

Whenever changes are made in the two graphs, AGG checks if the LHS or the RHS conforms to the type graph. The user is unable to insert elements in the two graphs that are not initialised in the type graph and the users are not allowed by AGG to create associations between nodes that are not initialised in the type graph. This is how AGG keep the source and target models consistent. In figure 4.6 we can see the tree based editor in AGG, that provides the type graph, the source graph and a list of transformation rules. When a new rule is created, both the LHS and the RHS are initialised. The users can then specify a graph structure that forms the LSH graph that AGG use to locate matching patterns in a source graph. The RHS graph represents the graph structure that the transformation system produces for each located match. AGG provides two visual editors for these corresponding graphs. However, there is also a graph that represents the intersection between the LHS and the RHS. In AGG this graph is edited by creating similar modeling elements in both the LHS and RHS graph and map these modeling elements with each other.
Figure 4.7 is a representation of the rule transformNextToSimple, with the LHS and the RHS graph. The LHS contains the graph structure that is used to locate matches while the RHS contains the graph structure that replaces the located matching pattern. For this rule the modeling elements that are represented in the LHS are also part of the graph structure in the RHS graph. Modeling elements that are part of both the LHS and RHS graph can be mapped together to specify for a transformation engine that these modeling elements defines a graph structure that is an intersection between the LHS and the RHS graph. In section 3.5 we introduced the concepts of single and double pushout of graphs for graph based model transformation tools. A double pushout of graphs includes this intersection graph for a transformation rule that makes it possible to preserve modeling elements that is part of both the LHS and the RHS. Modeling elements that is defined in the LHS graph and not the RHS graph are removed when the AGG transformation engine applies a transformation rule. For example the transformation rule in figure 4.7 locates the graph structure that the LHS defines in a source graph and inserts a new graph structure that the RHS defines in the source graph. This transformation rule will not remove any modeling elements once applied since we have specified that the modeling elements that is part of the LHS graph are also part of the RHS graph. A rule can also specify application conditions that can either be a Positive Application Condition (PAC) or a Negative Application Condition (NAC). Figure 4.7 has a NAC, activitySimple that makes sure that the LHS of the rule is translated only once for each pattern match found in the source graph. This is because for each applied transformation rule we preserve the LHS graph structure and therefore is a potential match the next time the transformation rule is applied. However, the negative application condition requires that the matching pattern should not contain any references and therefore is not a valid matching pattern. Through the use of these application conditions, the users can create restrictions to how each transformation rule should handle matching patterns in the source graph. A transformation rule can have multiple application conditions attached.

Application Control for the Transformation Rules

In subsection 3.4.3 we specified that the application control of a model transformation handles the location of matches and rule application control. Locating matches in AGG are designed by some non-deterministic search algorithms that the users have no control over. AGG does however provide the users with the possibility to explicitly specify how the transformation rules are applied. By default, the transformation rules are applied non-deterministically. This means that there are no pattern to how the transformation rules are applied and the transformation rules can be applied differently on different runs. This option is quite useful if the set of transformation rules are independent of
each other. AGG also provides other ways of applying rules such as applying rules by layers or by sequences. When the transformation is set to be applied by rule layers, then AGG introduce the users with an integer that specify transformation rules on different layers. This layer number will range from 0 . . . n, where the lowest number is the first layer and therefore the has first priority. If there are rules with the same layer number, then these rules will be internally applied non-deterministically. If the rules are applied by sequence then the rules will be applied from the first element in the tree based editor and applying the rest of the rules in sequence.

Translating the Source Graph

In section 4.2.1 we described that when applying a transformation rule a matching pattern is located in the source graph and a graph structure from the RHS is inserted in the source graph. This is special source models in AGG, because the source graph in AGG represents both the source model and the target model in a model transformation. AGG’s transformation system provides an in-place model transformation directly on the source graph. An exogenous model transformation that is specified in AGG usually include all located matches in the translated graph structure for each transformation rules. These modeling elements that represents the abstract syntax of the source model can then be removed through a set of transformation rules after the modeling elements that correspond to the abstract syntax of the target model is translated. This means that for an exogenous model transformation we should be careful when applying the transformation rules non-deterministically. The user can now either press Start Transformation or do the transformation one step at the time. For the first option AGG will apply one rule at the time until there are no more matching patterns located in the source graph. When AGG cannot find any more matches, the host graph is either correctly translated or there are errors in the rules. The user can also execute the transformation step by step. This will give the user the same result as the first option, but now the user can do one match at the time for each rule. AGG utilize both the single and double pushout approach when executing a transformation rule[36]. Like we discussed in section 3.5 the single pushout approach removes the graph structure from the LHS and inserts the graph structure from the RHS in the source graph. If the rules specifies an intersection graph between the LHS and RHS graph then the double pushout technique is used. AGG’s transformation engine interpret a transformation rule and applies the transformation rule accordingly. Another model transformation environment that similar to AGG utilizes the concepts of graph transformations is Henshin.

4.2.2 The Henshin Project

The Henshin project[57] provides a transformation language and a tool environment for defining model transformations for the Eclipse Modeling Framework. The Henshin project is part of the Eclipse Model Framework Technology (EMFT). EMFT acts as an EMF subproject for new technologies that extends and utilize EMF. The Henshin Editor was initially developed in a student project at Technical University of Berlin in 2010, and extended in the bachelor thesis [58] published by Johann Schmidt and the master thesis [59] published by Angeline Warning. The Henshin project provides a transformation language based on graph transformations that supports both endogenous and exogenous model transformations. With the help of a graphical editor, Henshin
provides the user with an intuitive approach to defining transformation rules. The Henshin tool environment provides a transformation engine, several editors and a state space generator.

**Graphical Editor**

Henshin model transformation environment is integrated as a plugin for the Eclipse Integrated Development Environment [60] and provides a graphical editor to create and modify transformation rules.

The users start out with using the Eclipse wizard to create an empty Henshin document. The Henshin document is based on the commonly known Extensible Markup Language (XML) [61]. If applicable a Henshin diagram file can be created based on the Henshin file that gives the users an intuitive approach to creating transformation rules.

The Henshin transformation file is represented in a tree based editor called the Henshin Model Editor. Figure 4.8 represents the editor that contains a list of transformation rules. These transformation rules are included under a Module element that represents the root element for a Henshin model transformation. For this specific example there are two external Ecore models included in the editor, more specifically the source and target meta-models. These meta-models are created based on the EMF standard for creating models and are independent of each other. Please note that a Henshin model transformation can include 0 . . . n models and therefore is not restricted to have exact one source and one target meta-model.

![Figure 4.8: Tree Based Editor for rules in Henshin.](image)

**Defining Meta-models**

The Henshin language requires a source and a target meta-model to be able to perform model transformations. The target meta-model can either be the same as the source meta-model or defined in another modeling language. Either way, before the users can start creating transformation rules, the meta-models has to be defined. To define these meta-models, Henshin utilizes Ecore, that is provided by the Eclipse Modeling Framework [62]. Ecore models can either be created using a tree based editor, called
Sample Ecore Model Editor or by using a graphical editor. While the graphical editor is optional, the tree based editor is mandatory for creating Ecore models, since this represents the Ecore model.

Initially the user has to create an EPackage element in the newly created Ecore model. Henshin interpret instances of this EPackage as EObjects and is what Henshin searches for when the user want to import an Ecore model. This EPackage element can have several child elements, like for example EClass, EEnum and EData type. For this specific example we only needed the EPackage as EObjects and is what Henshin searches for when the user want to import an Ecore model. This EPackage element can have several child elements, like for example EClass, EEnum and EData type. For this specific example we only needed the EPackage as EObjects and is what Henshin searches for when the user want to import an Ecore model. For each EClass element the users can specify a EAttribute that connects two EClass elements. This means that an EAttribute element defines relations between the nodes for the meta-models. To give an EClass element properties, the user can create an EAttribute element. This element can be typed, either by a predefined list of types or by defining user created EData types. For the purpose of this case study we only needed to name the different nodes and therefore we only needed the data type EString. Through the use of these Ecore elements, we can create the two meta-models from figure 4.2 and figure 4.3 that was previously presented in this chapter.

Defining Transformation Rules

Now we have defined the source and target meta-model, and imported both of the meta-models EPackages. We can now use elements from the two meta-models to create transformation rules in the Henshin transformation language. In Henshin, objects are referred to as nodes and links between objects as edges. From the meta-models these nodes represents the EClass elements and edges is a EReference between these EClass elements. A collection of these nodes and edges defines a graph structure. Each transformation rule in Henshin specifies two graphs that represent the LHS and the RHS. Note that the graphical editor provides an integrated view to creating transformation. And therefore Henshin handles assignment of modeling elements to the LHS and the RHS through the use of stereotypes. Figure 4.9 represents a visualization of the graphical syntax and includes a transformation rule, “transformSimpleActivity”. On the right side there is a palette that contains Henshin modeling elements and different EPackages. The first two EPackages represents modeling elements for the source and target meta-model. The Henshin Trace Model provides support for including traceable links for exogenous model transformations in Henshin. The Henshin Trace model provides a traceable link that keeps track of the translated elements during a transformation. This model consist of a single class Trace, that has two references called source and target. These references are of type EObject and therefore can refer to any EMF object. The Trace model is generic and therefore supports creation of traceable links between any Ecore models.
The Node, Edge and Attribute modeling elements are used to define the different transformation rules in Henshin. A new transformation rule in Henshin always have to start with creation of a new Rule element. Inside this Rule element the users are free to create nodes, and connect these nodes with edges. The nodes and edges defines a graph structure that is used to either locate matches in a source model or translate target modeling elements. Henshin makes sure that these nodes and edges conforms to their corresponding meta-models. Note that the Node and Edge modeling elements are special for Henshin and are used to create the content of the transformation rules. The Node element has a type that correspond to an EClass while the Edge element has a type that correspond to an EReference. Note that the Ecore models that are represented in figure 4.9 has a list of modeling elements that are typed by EClass. These modeling elements are a shortcut for Henshin to create nodes and creates a Henshin node with the corresponding type. The Attribute element can be used if attributes are defined for the classes that are imported. We will come back to the Unit element in the next section. Henshin distinguish if nodes, edges or attributes are part of the LHS and the RHS through the use of predefined stereotypes, or action types. Based on these action types Henshin automatically specifies if these modeling elements defines a graph structure that is used to locate matches in a source model or produce modeling elements for a target model. If the action type consist of the sequence “create”, Henshin knows that this element should be part of the replacement graph, or the RHS. While on the other side, the sequence “delete” should be part of the pattern graph, or the LHS. The “preserve” sequence is a bit more special, because nodes or edges in Henshin that is specified by this action type should be part of both the LHS graph and the RHS graph. This is done by putting the preserve element in both graphs and then create a mapping between these two elements to inform the Henshin Interpreter that this represents the same element. Henshin also has support for application conditions. The action types “forbid” and “require” are used for defining Negative Application Conditions (NACs) and Positive Application Conditions (PACs). These actions are supported for nodes,
edges and attributes. The example rule in figure 4.9 use four of these action types. The modeling elements in gray represents modeling elements that are part of both the RHS and the LHS graph, while the modeling elements in green are specified in the RHS graph. This specific transformation rule will locate a matching pattern in a source model that is described by an Activity modeling element. The positive application condition specifies that Henshin only should locate matches that is of kind “simple”. The negative application condition specifies that a located match that is described by the Activity class should not have a traceable link. The NAC specifies that the transformation engine does not locate duplicate matching patterns. The first time a match is located a traceable link is established. Now this specific match is no more a valid match since the NAC forbids the transformation engine to locate matches that already has established a traceable link to this modeling element. Note that we have a Trace and a PetriNets that is both a preserve modeling element. This is because these two are already translated by another transformation rule.

Application Control for the Transformation Rules

Transformation units are used to administrate the different transformation rules. Henshin provides several different units with different properties. Note that a transformation rule is also a transformation unit. This means that it is unnecessary to create a unit in Henshin if our model transformation only consist of one transformation rule. But if there are more than one transformation rule there has to be a control mechanism that determines how these transformation rules should be applied. An Independent Unit is applies rules non-deterministically and is a good solution if the order of applying the transformation rules is not important. But if the transformation rules requires a very strict pattern and are dependent of other rules, then a sequential unit are a safe way to apply rules. The sequential unit forces the Henshin transformation engine to apply rules in a sequential order. Figure 4.10 is an example of a sequential unit that will start applying rules at the black circle and follow the arrow through each given rule until it is finished.

![SequentialUnit main](image)

**Figure 4.10:** A SequentialUnit main that contains a sequence of rules.

If applicable a transformation unit can also consist of other units, for example if the user want to either iterate or loop through a transformation rules. The previous section described an example of a rule in figure 4.9. The sequential unit above the “transformSimple” represents a LoopUnit while the “transformStart” and “transformEnd” represents a single rule. The loop unit applies a single transformation rule until there are no more matches found in a source model. This is convenient for the rule, “transformSimpleActivity” since we specified that the rule should only locate matches where there exist no traceable link. Henshin also has two other units that can administrate transformation rules, namely ConditionalUnit and PriorityUnit. The ConditionalUnit follows a if-else pattern, and is used if the user want Henshin to choose between other units.
Translating the instance model

Now that we have defined the source and target meta-model, created a set of transformation rules and initialized a control mechanism for these rules it is time to apply the transformation rules. For Henshin there is two ways to do this. In Henshin the default engine for executing model transformation is the Henshin interpreter. This interpreter can be invoked either by using the a Eclipse wizard or programmatically using the Henshin API.

Using the Eclipse wizard is done by opening the Henshin file in the Henshin Model Editor and right clicking the root object and locate apply transformation. This will open a wizard where the user can choose a transformation unit. This will either be a single transformation rule or some transformation unit that applies all other units and rules. The user also has to select the instance model and can explicitly set parameters for the rules if this is applicable. If the parameter is set to Ignore then the interpreter will automatically match the parameter. Now the user has two choices, the first choice is to preview the result of the model transformation. This will either show the user a new window with the modifications to the model or a message that the rule or unit could not be applied. If the user press Transform instead of Preview, the model will be transformed and saved.

The interpreter can also be invoked programmatically, either as an Eclipse based application or as a simple Java application. Henshin provides a API that lets the users invoke the interpreter through the use of Java code. There is a class HenshinResourceSet that lets the user load and save models and transformations. When the instance model and Henshin module is loaded into the resource set, the transformation can be applied through the use of the Henshin Engine class. This is where Henshin finds and translates matches found in the instance graph. The user also has to specify the main transformation unit from the Henshin module. Both the engine and the unit can be loaded into the UnitApplication class. And this class has a method called execute that lets the user execute the model transformation. If the transformation was executed without errors, then the instance model can be saved with the translated changes. The Henshin API lets other users use the power of Henshin in their own program.

4.2.3 ATL Transformation Language

ATL\cite{63} (ATL Transformation Language) is a model transformation language and is an implementation of the QVT\cite{28} standard. It provides ways to produce a set of target models from a set of source models. ATL is maintained by OBEO\cite{64} and AtlanMod\cite{65} and was first initiated by the AtlanMod team, previously called the ATLAS Group, located at the University of Nantes in France. The initial version of ATL was created in 2004, where ATL became part of the Eclipse Generative Modeling Technologies (GMT) \cite{66}. The goal of GMT is to produce a set of research tools in the area of Model Driven Software Development. The ATL Integrated Development Environment (IDE) was later promoted for the Eclipse M2M project in January 2007.

There are developed several tools that has support for a declarative approach to model transformation. For the purpose of this paper, we will explain this approach with the focus around the Atlas Transformation Language (ATL). ATL is a hybrid model transformation approach, that is a transformation language that combines other model to model
transformation approaches. For example, ATL provides transformation rules that can be either fully declarative or fully imperative or a mixture of both.

![Figure 4.11: Model transformation process for Activity2PetriNets.](image)

Figure 4.11 gives us an idea of how the ATL transformation from an activity diagram to Petri net are handled. We want to generate a instance of PetriNets, that conforms to its own meta-model. This is generated from a source model, Activity Instance, that conforms to its respective meta-model. The created transformation Activity2PetriNets is expressed in the ATL transformation language, that conforms to its own meta-model. These three meta-models conform to the meta-model Ecore. So this makes Ecore a metameta-model to represent the meta-models of Activity, ATL and PetriNets.

ATL has to be configured properly before the user can execute a model transformation. In this configuration both the location of the source and target meta-model has to be specified. The user also has to specify what instance model that should be translated. And lastly the user has to create a new file that can be specified as the target instance model for the ATL run configuration. The user can then initiate the transformation by running this as an ATL transformation.

**Textual editor**

ATL can be compared to a programming language, because it is basically a transformation language that provides a concrete textual syntax. ATL is a text based transformation language, and is build around the Object Constraint Language (OCL) with some additional predefined functions. ATL transformations is stored in a file extension called “.atl” These ATL files can contain different kind of ATL units and are defined in its own distinct ATL file. These different ATL units are ATL modules, ATL queries and ATL libraries. Libraries can be used to create independent ATL libraries that can be imported to different types of ATL units. The module unit specifies the different application rules for a model transformation. And the Queries are used when the users want to compute primitive values from the source models.

Now that we have specified these three ATL units, we can describe shortly how we can use the ATL transformation language to create model to model transformations. For
our case study, we only need the ATL modules. An ATL module corresponds to a model
to model transformation. This unit enables developers to specify the way to produce a
set of target models from a set of source models. The source and target models of an
ATL module must be consistent with their respective meta-models.

Defining Meta-models

Defining meta-models for the ATL language is defined by the modeling language Ecore.
Since defining the meta-models are defined similar as Henshin, see chapter 4.2 for more
details.

At first, the user start out with a blank ATL file. Since we are working in the ATL
Integrated Development Environment for Eclipse, we want to start the document with
defining the path to the source and the target meta-model. The reason for doing this
is to achieve auto completion from elements defined in the Ecore meta-models. This is
convenient for the users when creating transformation rules.

![Figure 4.12: Two simple rules for Activity2PetriNets in ATL.](image)

Next the file is composed of four different elements. The first element is the header
section, where the user can give the module a name and name the variables corresponding
from the source and target models. The module name has to be identical to the name
of the ATL file.

We also need to specify the source and the target meta-model. From figure 4.12 we can
see that the target meta-model is initialised with the keyword create, and the source
meta-model is initialised using the keyword from. The user can also import some existing
libraries if needed. This import section is however optional. Importing meta-models are
handled a bit differently in ATL compared to Henshin. In ATL the meta-models are
imported explicitly while in Henshin they are imported implicitly before they can be
used in modifying the transformation rules. For ATL the user has to configure where
both the source and the target meta-model are located through a configuration page.
The next element is a set of rules that defines how the target models are generated from the source models. These rules are used to implicitly match source elements and produce target elements. In figure 4.12 we have examples of two rules, namely the rule for transforming the start activity and the rule for transforming the end activity. We can see that for each rule we specify what we want to translate from and what we want to translate to. We will describe transformation rules in more details in the next section.

The last element in a ATL module is a set of helper functions. This collection of helpers can be compared to Java methods. These helper methods can be used to make the transformation rules easier to read.

Transformation Rules

A rule in ATL describes how a target model should be generated from a source model. In ATL there are three kinds of rules, the type matched rules and the lazy rules are both fully declarative while the called rules are imperative. These rules has an input pattern and an output pattern. The input pattern can have a list of source model elements that is part of a rule in ATL by defining several input pattern elements. Each input pattern element has to have a mandatory type that corresponds to a metaclass defined in some meta-model. Each rule corresponding input pattern can also specify optional conditions that are expressed as OCL expressions. Both the type and an optional condition specifies which elements from the source model that is matched for each rule. The output pattern defines how the target model elements are created from the input model.

The matched rules provides an declarative approach to creating transformation rules in ATL. The users can specify from which kinds of source elements the target elements can be generated from and how the generated target elements should be initialized. A matched rule finds a match according to the type of source model element and generate target model elements from these matches. A new matched rule is defined by the keyword “rule” and has two mandatory and two optional sections. The mandatory sections specifies the input pattern and the output pattern while in the first optional section the users can declare and initialize local variables. Note that these variables can only be used in the scope of each rule. The second optional section includes an imperative section The type that is introduced in the input pattern conforms to a meta-element in a meta-model of the source model. This rule will then generate target elements according to each match in the source model.

Figure 4.13 shows a simple rule, Activity2StartPlace that wants to translate Activity source elements to some target elements. This rule specifies the keyword from for the input pattern and to for the output pattern. For this example we want to find matches for one source element that is of type Activity that conforms to the meta-model Activities. We also provide additional properties for this input source element, where we only want to find matches that conforms to the type Activity and has the name “start”. The rule specifies that we want to generate three target pattern elements p, t and a_t from this matching type. These generated target elements conforms to the meta-model Petrinets and specifies that these generated types should generate attributes from the source pattern element. The generated target model elements is initialized with attributes from the matched source pattern element.
If applicable the users can add an optional condition for each rule to check for certain matches for this input element. This condition is expressed as an OCL expression and gives the user the possibility to restrict the searches of the source elements.

The second type ATL rules are **Lazy rules**. These lazy rules will never be applied when a model transformation in the Atlas Transformation Language is executed. These lazy rules can only be applied to a model transformation when they are called from another of the two rules. These lazy rules are created similar to the matched rules.

The third and final type for an ATL rule is called **Called rules**. A called rule has to be called from an imperative section from either a match rule or from another called rule. A called rule is created similar to a matched rule, namely with a `rule` keyword. One thing that is special with a called rule is that it does not have to match source elements from the source model.

### Execution of an ATL transformation

Figure 4.14 describes the architecture of the transformation language. From the figure we can see that we have an association between EMF and Ecore models. This are the meta-models that are expressed using EMF’s Ecore model. These meta-models are then translated through a model handler that compiles these Ecore models to the ATL Virtual Machine. Where these meta-models can be used both in creating ATL programs and in ATL’s internal interpreter. The ATL compiler translates the ATL file into a new ASM assembler file, that ATL can use to launch a model transformation. This assembler file contains the compiled code of the corresponding ATL file.
The default semantics for executing a set of transformation rules specified in ATL can be described in three phases. See ATL User Manual for more information.

The first phase is an initialization phase. This phase consists of amongst other things to initialize the trace model and the module of the ATL transformation. The trace model in ATL has one important function, and that is to create a trace link that points to the matched source input elements and the corresponding generated target output elements. The trace model in ATL works as an implicit tracing mechanism that specifies relationships between the source element and its corresponding target elements by using a native type called ASMTransientLink. For every time a transformation rule is matched to a source element, one ASMTransientLink is created. To this transient link the name of the transformation rule provided together with the source element and the target elements. These links are added to a collection that is stored internally for ATL. However, as shown by Andrés Yie and Dennis Wagelaar, that gaining access to these ATL traces can be done explicitly by creating transformation rules that generates a tracing model based on the internal tracing information provided by ATL.

The next phase consists of finding matches in the source pattern of the matched rules. This is done by the ATL transformation engine that searches for valid matches. A match is valid when all input pattern elements are found amongst the source model elements and any OCL expression for that matched rule is valid. The transformation engine also allocates the target model elements based on the declared output pattern into memory. At this point the target model elements are only allocated, they are initialized in the final phase. For each match found, there is created a trace link that has a source link to the matched source elements and a target link to the generated target elements. The generated target elements are not given any attributes or properties in this phase. This phase creates target elements from matches found, and create a trace link between them.

The final phase of for executing an ATL module is to initialize the target model elements. At this stage each allocated target model element are given attributes and features that corresponds to the matched rule. The ATL transformation engine now use the trace
links to determine the matched source elements and the generated target elements. This operation is called resolveTemp, that returns the reference from the target model elements that where generated in the second phase and to the corresponding source model element. Now that these three phases is finished the ATL transformation engine can execute the imperative code sections defined for the module.

### 4.3 Model transformation environment for DPF

After working with the three model transformation environments in the previous section we decided to try and integrate Henshin with DPF. In this section we will describe why Henshin is the better choice of the three considered environments to integrate with DPF. Henshin is a relatively new installment in the world of model transformations. The environment was initially created three years ago, in 2010 and is marked as an Eclipse Incubation project. The purpose of the incubation phase is to establish a fully functioning open-source project. In theory an integration of Henshin with the DPF should be possible, since Henshin applies model transformations based on Ecore models and DPF models are basically represented as Ecore models. This presents a problem with integrating AGG with DPF. In EMF the root of all modeling objects is an EObject that has no references to a Java Object. AGG could be integrated with DPF, but the problem is that this would require an extensive amount of manual coding. We could use AGG as a general purpose graph transformation engine in a java applications. We would have to create the source model as an AGG graph and a type graph based on the source and target modeling formalism that DPF provides. AGG provides an API that conveniently let us create type graphs, source graphs, transformation rules and application conditions.

Figure 4.15 represents a proposed solution how to integrate AGG together with a DPF transformation tool. The figure represents a source modeling formalism on the left side, a target modeling formalism on the right side and a model to model transformation done with AGG in the middle. The figure informs us that we have to generate four models to be able to do this in AGG. First we create the abstract syntax for an AGG source graphs by generating a joined type graph from a source modeling formalism and target modeling formalism. Then we have to generate the source input specification into a source graph that at the same time conforms to the joined type graph. Note that we do not mention the transformation rules since we have to generate these regardless of what model transformation environment we integrate with the DPF workbench. After the AGG transformation engine have executed the transformation rules we have to generate a target specification based on the produced target graph. This leads to some potential problems. The program that generates a source graph and a target specification has to
be solid and not contain any flaws. Another problem is to keep the models consistent throughout the model transformation. How can we be certain that the target graph is consistent with the target specification? It is easy to lose consistency when changing a model manually from a target graph to a target specification. We could use AGG to do this, but that leads to many potentially factors that could go wrong. With Henshin and ATL we are not required to do anything extra with these models. Since both environments has support for including Ecore models as meta-models and requires an instance model of an Ecore model as a source model to apply a model transformation. Therefore AGG can be integrated with EMF with some additional work, but Henshin and ATL is a more viable choice for DPF, since we can use this Metamodel.ecore as a meta-model and the source specification as input model directly in the other two environments.

Now we need to decide if we want to try and integrate the hybrid model transformation environment, ATL or the graph based model transformation environment, Henshin. In section 2.4 we discussed that a DPF model is an extension of the Generalised Sketches formalism which is basically a directed graph. Then a specification consist of a set of nodes, edges and two functions that preserve a source and a target node for all edges. A model transformation in Henshin is based on the concepts of graph transformations and category theory. We can then be certain that Henshin can interpret a source specification as a directed graph. Henshin transformation is also based on the two graph transformation styles single (SPO) and double pushout (DPO) that we discussed in section 3.5. And we recall that the DPO approach provides a dangling condition that ensures that a model transformation does not result in any edges that are missing a source or a target node. We want to create a tool for the DPF workbench that provides the following.

- **Concrete Graphical Syntax.** We want to be able to create transformation rules based on graphical syntax that the DPF Editor provides.
- **Generic.** We want our tool to work for an arbitrary source and target meta-model regardless of abstraction layer.

The tool is required to create a set of transformation rules based on some model transformation language and we want these transformation rules to be generic. This means that we create a set of transformation rules based on an arbitrary source and target meta-model. The only aspect of these meta-models that is consistent is that they contain a list of nodes and arrows. This means that regardless of abstraction layer a specification is specified by a set of nodes and arrows. The reason for why we decided to try and integrate Henshin within the DPF workbench is provided in the three items underneath.

1. We want to create a tool that use a simplified version of the DPF Editor to create transformation rules that provides a concrete graphical syntax. DPF models are already based on category theory and provides a graphical syntax.

2. Through the use of the Henshin meta-model we can generate a set of transformation rules that are based on the abstract syntax of the source and target specification. We can define a set of transformation rules in Henshin as a java application with the help of the API that Henshin provides.
3. We can utilize the concepts around graph transformation that provides a left hand side, a right hand side and an intersection graph. Through these three graphs we can in Henshin use the single or double pushout approach when applying a set of transformation rules.

The problem with integrating Henshin with DPF is that Henshin is based on the EMF technology, and therefore utilize OMG’s MOF. Henshin supports out of the box model transformation that translate instance models that conforms to an Ecore based meta-model. These instance models provides the concrete syntax of a modeling language and are described by a corresponding meta-model that represents the abstract syntax. This meta-model is provided accordingly to the second layer of the Meta-Object Facility. This means that Henshin provides model transformation according to EMF’s two layered modeling environment. DPF on the other hand provides initialisation of a potential endless hierarchy of meta-modeling, and therefore does not match the steps MOF provides to create the abstract syntax for a Domain Specific Language. We know that a transformation rule in Henshin requires references to meta-modeling elements from a source meta-model and a target meta-model. What makes a DPF specification special is that it is an instance model of both an Ecore based meta-model and another specification. This means that a specifications concrete syntax is typed by the abstract syntax of a specification that is one abstraction layer higher. In DPF we can create an arbitrary level of meta-models and therefore two different Domain Specific Modeling Language can be defined over a different abstraction layer hierarchy. The Henshin environment has strict guidelines on how models are imported and used. These models are required to be created accordingly to the Ecore model provided by EMF. Henshin can then utilize these models to create a graph pattern that structure both the LHS and the RHS graph of a transformation rule. Now the LHS graph contains a graph structure that is is used by the transformation engine to locate matches in an instance model that conforms to the specified Ecore model.

For our tool we can structure a set of transformation rules in Henshin based on this common meta-model, Metamodel.ecore that all specifications $S_1...n$ conforms to. We have to threat all specifications similar if we want the tool to provide a generic model to model transformation. The challenge with integrating Henshin in a language workbench that provides meta-modeling at arbitrary layers of abstraction is not in the source specification we want to translate, but in the instance specification that the source specification corresponds to. This proves to be a problem for Henshin, because we cannot import an instance model of an Ecore based meta-model into the Henshin model transformation environment. We can do changes to an instance model by using Henshin, but the transformation language can only import and utilize models that conforms to the Ecore meta-model. To solve this for DPF specifications we expand transformation rules in Henshin with application conditions. This means that we restrict the LHS graph to locate matching modeling elements in an instance source specification based on the abstract syntax that another specification provides. The next chapter provides an explanation on how we integrated Henshin for a transformation tool that provides model to model transformations for the DPF workbench.
Chapter 5

Problem Solution

5.1 Integrate Henshin with DPF

DPF is a framework where it is possible to create arbitrary levels of meta-models. That gives the users the freedom to define a well formed domain specific modeling language and to define constraints for each specification at each level of meta-modeling. The framework provides the possibility to define specifications that specify underlying specifications. Where each specification $S_{n+1}$ defines the abstract syntax for a specification $S_n$. For DPF to be a framework that follows the visions of model driven engineering it needs to have support for automation of specifications over different levels of abstraction. It already has support for some cases of model transformations. There is one natural model transformation for DPF when specifying a new specification. A new specification will always be specified by a modeling language that corresponds to a specification $S_{n+1}$. These specifications may either be a user created specification or the default specification provided by the framework, that conforms to itself. The creation of a new specification can be viewed as the first support for automation over levels of abstraction for models that the Diagram Predicate Framework provides. In 2012 Anders Sandven published his master thesis\cite{52}, where he implemented support for generating source code with the DPF Editor. DPF does not provide support for applying an exogenous model transformation to a specification described in one domain specific modeling language to a model expressed in another domain specific modeling language. To achieve this we want to integrate Henshin transformation language\cite{67} to the framework.

\begin{figure}
\centering
\includegraphics[width=\textwidth]{figure5.1.png}
\caption{Using Henshin transformation language to translate a specification $S_n$.}
\end{figure}
Chapter 5. Problem Solution

Figure 5.1 explains how we want to integrate the Henshin model transformation language with the Diagram Predicate Framework. Henshin provides a transformation language and a transformation engine. We use the Henshin transformation engine to read an instance specification $S_n$ and write an instance specification $S_m$. To achieve this the transformation engine executes a set of transformation rules written in the Henshin Transformation Language. These transformation rules refers to the abstract syntax for the specification $S_{n+1}$ and specification $S_{m+1}$ that the source and target model are typed over.

Figure 5.2: Progressively workflow for the problem solution.

Figure 5.2 provides a diagram that describes in five steps how the editor progress from creation and execution of transformation rules. We can see that this diagram is extended from the previous figure 5.1. The figure then explains that step 5 use the Henshin transformation engine that reads a specification $S_n$ and writes a specification $S_m$. But before we can apply the actual transformation we have to consider how the DPF Transformation Editor provides a set of Henshin transformation rules.

1. At the first step we still have to provide a source modeling formalism that contains a specification $S_{n+1}$ and a target modeling formalism that contains a specification $S_{m+1}$. These specifications has an underlying graph that contains nodes and arrow that represents the abstract syntax for the source and target specification.

2. Step 2 consist of creating a new transformation model in the DPF Transformation Editor. This new transformation model has references to a source modeling formalism $S_{n+1}$ and a target modeling formalism $S_{m+1}$. With both the target and
source modeling formalism we create a $\mathcal{S}_{n+1} \cup \mathcal{S}_{m+1}$ specification that we use for typing purposes for the transformation rules. An empty correspondence graph is also generated.

3. Step 3 focus on creating the transformation rules through defining a set of productions, where one production represents one transformation rule. A single production specifies a LHS, RHS and an intersection graph that refer to this common type specification, $\mathcal{S}_{n+1} \cup \mathcal{S}_{m+1}$. At the same time corresponding objects are initialized by the user to specify the relation between source modeling elements and target modeling elements.

4. In step 4 we generate a set of Henshin Transformation Rules from these productions and capture the correspondence between objects by specifying traceable links.

5. In the final step we can apply these transformation rules to a Henshin transformation engine and produce a target specification $\mathcal{S}_m$.

One major challenge was processing Henshin transformation rules from modeling elements that is represented in the source and target modeling formalisms. These five steps describes the workflow of the DPF Transformation Editor. In the next sections we will explore the most essential functionality of these five steps and explain how we can integrate Henshin with the DPF workbench. But first we will describe how a transformation rule is modelled in the Henshin model transformation language.

### 5.2 Henshin meta-model

The Henshin transformation language provides a meta-model that is an EMF based model and uses the Ecore meta-model for typing purposes\[67\]. Since this model is created based on EMF we know that EMF will generate interfaces and a factory that we can utilize to implement Henshin transformation rules in Java. We can specify a pattern graph and a replacement graph for each transformation rule based on the factory class that Henshin provides. In the following we will address what elements a transformation rule in Henshin consist of based on the Henshin meta-model for a transformation rule represented in figure 5.3. The figure is obtained from a paper that Thorsten Arendt, Enrico Biermann, Stefan Jurack, Christian Krause, and Gabriele Taentzer published in 2010 on the Henshin transformation language where they provide the meta-model for defining a single transformation rule\[67\].

![Figure 5.3: Henshin meta-model for a transformation rule.](image-url)
A Rule in Henshin represents a transformation rule that has a name, a description and three properties. The first property disables or enables the transformation rule, while the two other properties lets the user enable or disable injective matching and the check dangling condition. The rule class works as the root for all other elements that are represented in figure 5.3. A new rule defines a left hand side and a right hand side Graph. The content of the LHS graph represents the model pattern used to locate matches in an instance graph while the RHS represents the model pattern that is created. The LHS and RHS graph is formed by creating nodes and edges. Nodes refers to objects in an instance graph and edges refer to references between objects. An edge has a source and a target node, while a node can have a collection of incoming and outgoing edges. The nodes can also have a set of attributes attached. Nodes, edges and attributes all have two common properties, and the first one is that they all have a type.

Figure 5.4 represents a small fraction of the Ecore meta-model and how Henshin modeling elements are typed by either an EClass, EReference or EAttribute. For example a Node that is typed by a specific EClass will only be matched to objects of this type in an instance graph. These nodes and edges are represented under a graph and form a pattern. Together with the LHS and the RHS these patterns is either used to find matching patterns in a source model or to create the corresponding pattern for a target model. The second property that these three have in common is that they have an action type. Action types are predefined stereotypes for Henshin and specifies how these three Hen- shin modeling elements of a graph in Henshin behaves when applying a transformation rule. An action type could specify if a graph element is part of an application condition, the replacement graph, the pattern graph or an intersection graph. A Mapping specifies how Henshin defines the intersection graph. This is Henshin modeling elements that should be included in both the LHS and the RHS graph. This means that these objects should be part of the matching pattern, but should not be deleted. A mapping has two properties, namely an origin and an image. The origin property refers to a given node from the LHS graph, while the image property specify a mapping to a node in the RHS graph. So far we have a rule that can have two graphs and a set of mappings.

A rule can also specify a Formula that determines restrictions for match searching for this rule. A Formula modeling elements is a child of a graph and defines application conditions in Henshin. This formula class can either be an u-nary logical operation, a binary logical operation or a nested condition. The first logical operation operates on a single operand while the second operates on two operands, where these operands are represented as a conditional statement that is either true or false. A rule can be applied to a instance graph if and only if all application conditions are valid. We can basically have a unlimited nested formulas in Henshin, since a binary formula can have a right and left Formula, that can again be of type binary formula. Henshin however is only...
concerned whether this formula is valid or invalid when a transformation rule is applied. A nested condition is required if we want to have nodes that are part of the LHS graphs or the common graph, that is the intersection of the LHS and RHS graph. A nested condition provides a graph and a set of mappings to elements that are part of the LHS or common graph. This graph is child of a nested condition and contains nodes, edges and attributes that form a structural pattern that specifies an application condition. We can observe that transformation rules can have several number of application conditions. A binary formula can be of type Or or And and provides the possibility to nest other binary formulas. If the structure of a binary formula is the latter, then all the application conditions from both the right and left formula has to be be valid for a transformation rule to be applied to a instance graph.

5.3 DPF Transformation Editor

With the Eclipse Modeling Framework we created an Eclipse plugin where users can create and modify transformation rules. Figure 5.5 provides the structural data model that we use to generate code for the model implementation and the plugin implementation. The two classes Transform and Production are the two domain classes that together defines this domain specific modeling language that lets users create transformation rules. The Transform class represent the DPF Transformation Editor and has a source meta-model and a target meta-model, that corresponds to a source specification and a target specification. If these two models are the same model, then the model transformation is an endogenous model transformation and if the models are different, then we have an exogenous model transformation. We also have the file location on the storage unit for the source and target meta-model. The rules represents a collection of the transformation rules. These rules are typed by a Production and represent one single transformation rule. A transformation rule has a name and contains a graph that is stored internally for each rule. This graph contains a pattern of nodes and arrows that the user can edit to form a LHS graph and a RHS graph. A single Production also has several collections that contains nodes and arrows. These collections are utilized by Henshin to generate transformation rules.

Figure 5.5: The domain model to create a DPF model transformation editor.
The user has to invoke the file creation wizard for the DPF Transformation Editor. Other than choosing a project folder and a name for this new editor file, the user has to specify what model is the source meta-model and what model is the target meta-model. If the user do not specify a target meta-model then the file creation wizard will interpret this as an endogenous model transformation.

The DPF Transformation Editor plugin has two editors that users can interact with. The first is the master editor for the plugin and contains a list of the transformation rules, where users can create, read, update and delete rules. The second editor is administrated by the master editor, and each time a new transformation rule is chosen, a simple version of the DPF editor is opened with its corresponding transformation rule. This editor is created from the Graphical Editing Framework (GEF) and is a graphical editor that includes a palette. This palette is the same palette that is used in the DPF Model Editor and contains modeling elements from the source meta-model and the target meta-model.

These nodes and arrows are used to create the internal graph for each corresponding rule. For each rule the users can uniquely map nodes and arrows to three subgraphs represented as lists. Figure 5.6 represents the left, right and common subgraphs, where each corresponding subgraph has a list of nodes and arrows. Each subgraph represents a different part of a transformation rule according to graph transformation. The left subgraph represents the LHS graph of a rule, while the right subgraph represents the RHS graph. The common subgraph represents the intersection between the pattern graph and the replacement graph. It is vital for the model transformation to work that all the nodes and arrows are mapped to one of these three graphs. This is entirely up to the user, because the nodes and arrows from the LHS graph have to be created in such a way that the graph can be matched in an instance graph.

Now that a list of transformation rules has been specified the user has to initialise the model transformation environment. This is done through three steps.

1. **Generate Correspondence Graph.** The first thing the user has to initialise a graph that contains the correspondence objects. This is important since Henshin cannot foresee how modeling elements from the source model are related to modeling elements from the target model. This relation has to be specified before we can create the Henshin model transformation environment.

2. **Generate Henshin Rules.** Before we can use the Henshin model transformation language we have to provide a module that contains a set of transformation rules. And to achieve this we have to translate our transformation rules we create in the editor into Henshin executable rules.
3. **Apply Model Transformation.** After the user has created a correspondence graph that bind objects from source and target model and translated transformation rules from the editor to Henshin executable transformation rules. We can now apply the transformation rules through programmatically invoking the Henshin interpreter.

### 5.4 Generate Correspondence Graph

The Henshin transformation language refers to modeling elements from a source specification and a target specification when creating transformation rules. But we have to define how modeling elements from a source model is translated to a target model. Henshin is unable to figure out how source modeling elements are related to target modeling elements unless this is provided explicitly. We can create a new DPF model that presents all the nodes and arrows from the source meta-model and target meta-model as nodes. Figure 5.7 express how we want to implement this for our model transformation environment.

![Figure 5.7: The solution expanded with a specification for the correspondence objects.](image)

Now we have a created a new DPF model contains a list of nodes for all node and arrow types from the source specification $\mathcal{S}_{n+1}$ and target specification $\mathcal{S}_{m+1}$. We then provide a new modeling element that is a bridge element between a source and target modeling element. We can specify an arbitrary number of these elements that binds nodes and arrows from a source model to nodes and arrows from a target model. This DPF model specify the correspondence graph between source and target meta-models. We can now refer to this DPF model when creating Henshin transformation rules to extract the corresponding objects. We can also do this explicitly when creating the transformation rules in the DPF Transformation Editor by modeling a new trace object that represents a trace between a source modeling element and a target modeling element. We use this trace object or the correspondence graph to determine how we translate a DPF model. We create a trace object that has a source reference to every matching node and arrow that the transformation engine can locate and a target reference to the created nodes.
and arrows. The next section will address these traceable links in more detail together with how we generate Henshin transformation rules.

5.5 Generate Henshin Rules

We utilize the meta-model represented in figure 5.3 to create transformation rules in Henshin. We use the factory that is provided by EMF for Henshin model transformations to achieve this. We start with creating the root element that is required for a Henshin model transformation and import EPackage that is needed to define the content of a transformation rule. We need to import two models if we want to translate a specification with Henshin. The first model is the corresponding meta-model for all specifications and the second model is the meta-model for including traceable links in Henshin. We will describe the purpose of these traceable links in more detail in subsection 5.5.1. The transformation language requires models that define the abstract syntax for an instance model to be able to specify modeling elements for both the LHS and the RHS of a transformation rule. We can use meta-elements provided by these two models when defining new nodes, edges and attributes in Henshin. These types are EClass for nodes, EReference for edges and EAttribute for attributes.

For Henshin we create one rule for each production provided by the editor, where the name of the rule is acquired from the production. Henshin provides a LHS, a RHS graph and a collection of mappings for each rule. We can create a graph structure for the LHS and the RHS based on the subgraphs that a production provides. Modeling elements that form a pattern in the LHS are used to find a match in a source model, while modeling elements that form a pattern in the RHS are used to create new elements or replace these elements. Henshin also include an intersection graph for each rule. This graph is not represented as a physical graph like the LHS and the RHS are, but is represented as an underlying graph that is formed from these two graphs. The intersection graph is represented by having elements in both the LHS and the RHS graph with mappings that distinguish that these elements are one and the same. Now we have the LHS graph, the RHS graph and the intersection of these two graphs, which was mentioned in section 3.5. In this section we introduced double and single pushouts of graphs. Henshin has an arbitrary mixing of these graph transformation styles.

For each rule we created in the DPF Transformation Editor we have defined a pattern, that either corresponds to a left hand side, a right hand side or a common graph. This pattern consist of nodes and arrows that together form a graph. For each node and arrow, we create a Henshin node that is either typed as a Node or as an Arrow. An Arrow has to be represented as a Henshin node since it is defined in the meta-model for a specification as an EClass. Now we have to connect Henshin nodes with edges. An edge has three parameters, namely source, target and reference. In Henshin we create an edge with a source Henshin node and a target Henshin node. How the reference is typed depends on how the source and target node refer to each other in the specification meta-model. Figure 5.8 explains a simple example on how the relationship between a node and an arrow are handled for a specification.
Chapter 5. Problem Solution

Figure 5.8: Example of how nodes and arrows are related for a specification.

This is a representation on how DPF models relate to one another. We can have an arrow that has a target and a source node, while every node can have a list of both incoming and outgoing arrows. So this means that a Node and an Arrow have a similar relation in DPF models, where source and outgoings references represents the same relation but are typed differently. It is however easier to couple with the arrows when creating transformation rules, since an arrow has an one-to-one relationship, meaning that an arrow has one source node and one target node. How the typing for an edge in Henshin is specified depends on the Henshin source and target node. These nodes are typed by a corresponding EClass type from the specification meta-model, that is a Node and an Arrow. An edge in Henshin can specify a relation between two other Henshin nodes depending on how references between Node and Arrow are typed. According to figure 5.8 we have two references between arrow and node and two references between node and arrow. If the source Henshin node for an edge is typed by Arrow then the available references are source and target. On the other side if the source Henshin node is typed by Node then we have a zero to many relationship in the two references incomings and outgoings. When we define relationships between two Henshin nodes we use the source and target reference. This is because this is an one to one relationship between two nodes and therefore we can always find the source and target node for a given arrow. This means for every Henshin node that are typed by Arrow we have to specify two relationships for this Henshin node. This is done by creating two edges in Henshin, where one refer to source node while the other edge refer to target node. This is achieved by specifying the Henshin node that is typed by Arrow as source for both edges and switch between source and target as reference for each target Henshin node.

At this moment the pattern on the left hand side and the right hand side graph are not typed. The pattern conforms to the meta-model for a specification, but this is the case for all specifications, on every level of meta-modeling. However, these specification models are typed by another specification, and this is where we can retrieve the types for every node and arrow. In the specification meta-model both the Node and Arrow class has a reference type to another Node and Arrow. Figure 5.9 represent the LHS for the DPF Transformation Editor that we want to generate Henshin rules from. The idea is to create an application condition for every node and arrow with their corresponding type node and type arrow. The type nodes and arrows have an attribute called name and is a string. We can use this attribute to specify a positive application condition in Henshin. A positive application condition in Henshin has an action type, require. This means that all application conditions for Henshin that is typed by this action are required to be valid when searching through a source model for a transformation rule to be applied.
This also leads to an important change in our Henshin rules, because we have to include one more node and edge for every node and arrow. We have to create a new Henshin node that represent the type node and type arrow. We also have to create a new Henshin edge that define that this Henshin node is typed by another Henshin node. This is because when Henshin is locating matches in an instance graph we want the transformation language to locate matches for nodes or arrows that are typed by a specific node or arrow. Figure 5.10 explains how we solve this in Henshin. We have a pattern graph or LHS on the right and an application condition graph on the left. This specific transformation rule in Henshin specifies a simple LHS graph that has an Arrow1 element with a source Node1 and target Node2 elements. Note that here the Arrow1 element is represented as a node and not as an arrow like figure 5.9. The reason for this is because an arrow is represented as an EClass in the common meta-model. For this example we focus on the Node1 element.

We discussed in section 5.2 that an application condition is represented as a Formula in Henshin, and to solve typing of nodes and arrows in DPF we need to create this Formula as a nested condition. This is because a nested condition provides a set of mappings and a graph, where we can define nodes, edges and attributes. To be able to map Henshin nodes is essential for creating an application condition. We need to make sure that an application condition is applied to a corresponding matched modeling element for a source model. This is achieved by mapping Henshin nodes that are part of the graph in a nested condition to Henshin nodes that are part of the graph pattern that is used to locate matches. If we refer back to figure 5.10 we can see that the pattern graph has a Node1 that are typed by a T_Node1. We then create a graph for a nested condition that contains these two nodes and create a mapping from nodes in the application condition to the nodes in the LHS or intersection graph. It is important to specify that application conditions can not be defined for the replacement graph and is not needed either, since the replacement graph is what we want to translate depending on how many times we can
locate a match for the graph pattern that the LHS provides in an instance graph. Now we need to specify what an application condition should restrict when searching through matches, and this is the name attribute of the type element. This application condition can either be a positive or negative application condition. In this case we want the name attribute to be a positive application conditions that returns true for every matching type element located in an instance graph. We can specify several application conditions for a rule, and it depends on the graph structure of the searching graph. We define a new application condition for each nodes and arrows that are part of the LHS graph, since these modeling elements can form a directed graph and each modeling element is typed by a modeling element from the source meta-model. All of these application conditions has to be true for a located match to be a valid match. Now we will expore how we also implement negative application conditions for our model transformation environment with traceable links.

5.5.1 Traceable links

As we discussed in chapter 3.2.7 a traceable link works as a footprint when executing a set of transformation rules. Henshin provides a traceable link implementation through the Henshin Trace model. This is a simple meta-model for defining traceable links and can be imported for any Henshin module. The Henshin Trace model provides a Trace modeling element and provides an unique traceable link between a source modeling element and target modeling element. The source and target modeling elements can be any classes that conforms to the Ecore meta-model. We create a traceable link for every Henshin node we have included for the LHS graph. The nodes in the LHS graph are the source modeling elements for a Trace modeling element while nodes in the RHS graph are the target modeling elements. Now we have an unique link between a matched node from the LHS graph and a produced node for the RHS graph for every time a transformation rule is applied. These traceable links are represented in the replacement graph the first time that a connection between two nodes are initialised. This means that the traceable links are actually translated when a transformation rule is applied and stored in the translated graph. Next time we want to refer to a traceable link between modeling elements where a transformation rule has been applied we have to make sure that the trace object is created both in the LHS and the RHS with a mapping between them. Because together with a negative application condition this traceable link will make sure that we only translate located matches in an source model once. This can be achieved by defining a negative application condition that forbids Henshin to create a traceable link. We create a nested condition similar to the previous section, but for this case we want the application condition only to return true for all matches that does not contain this graph pattern. This is very convenient when applying a set of transformation rules, because we have already stated that a traceable link is created when a transformation rule locates a match in an instance graph. This means that we create unique traceable links between all nodes in the pattern graph that is matched in an instance graph and the nodes that we create. It has to be noticed that the source and target nodes of a traceable link has to be typed by the EClass modeling element that Ecore provides. We can now execute the set of transformation as long as we want and be safe that we will not execute matching pattern in an instance graph more than once. The reason that we can make this statement is because when we find a match for the first time then there exist no traceable link between modeling elements. But once the transformation engine execute this rule, then a traceable link is created between the
matching nodes on the left side and the corresponding modeling elements on the right side. And now the transformation engine are unable to locate this match for a second time because we have restricted the transformation rule to not include matches that has a traceable link to the source node that are part of the LHS graph. Now we will describe more in detail how we apply these transformation rules.

5.6 Apply Model Transformation

5.6.1 Rule Application Control

Now that the DPF Transformation Editor has generated a set of Henshin transformation rules the transformation engine is ready to apply these rules to a source model. The Henshin module we generated in the previous section now contains a set of transformation rules that are specified in the Henshin Transformation Language, that we described in figure 5.1 in the first section. The Henshin Transformation Engine can now execute this generated module by explicitly invoking the Henshin interpreter. The interpreter requires a module, a graph that contains the source model and a Henshin unit before it can be applied. For our solution we have created a transformation unit that executes a set of transformation rules in the same order that the DPF Transformation Editor provides, and is called a Sequential unit. A transformation unit in Henshin is an implementation of a rule application control system that we described in a more general term in section 3.2.3. A transformation unit in Henshin is an executable part that the transformation engine can interpret and apply rules accordingly. It is important to specify that a transformation rule itself in Henshin is a transformation unit, and can therefore be executed by Henshin’s transformation engine. But a Henshin transformation rule does not provide any control mechanism for it self or other rules when executed. A transformation rule will therefore only locate one single match if we invoke the Henshin interpreter on a single rule. This is one reason for why we want to specify a transformation unit that has some unique properties that a single transformation rule does not provide. Some Henshin transformation units have the possibility to have other transformation units as subunits. The Sequential unit that the module provides works as the master unit for applying the transformation rules. For each transformation rule we created in the previous section we define a Henshin Loop unit. This unit can only contain one single subgraph, and that is the corresponding transformation rule. The Loop unit is executed for as long as there are any matching modeling elements in an instance graph and will locate matches an unlimited number of times unless we provide any mechanism to stop the unit. This is where the negative application conditions that we described in the previous section plays a vital role. Because the negative application condition specifies that a transformation rule will only be applied unless there exist no traceable links. The first time the transformation engine locates a match for a transformation rule it will create a traceable links that connects the matching modeling elements and the created modeling elements. Now the next time this specific match is located the application condition will not be valid since now there exist a traceable link that has a reference to a modeling element in the source model. We can now apply these repeatable units for all transformation rules as long as the input graph does not contain a traceable link for a matched modeling element.
5.6.2 The Transformed Model

For all matches found in a source model we do some changes depending on how the RHS graph is specified. These changes are specified as new DPF modeling elements after applying a set of transformation rules. The next step is to make sure that the produced modeling elements are type correct. This means that the target model is required to conform to a target modeling formalism. Figure 5.11 represents the result of a model to model transformation.

The transformation EGraph represents the source model as we mentioned in the previous section. The Henshin interpreter will execute transformation rules on this transformation graph until there are no more valid matching pattern located in the source model. The produced target modeling elements that are included in the transformation graph after rule execution conforms to a joined modeling formalism. However, we want these modeling elements to conform to a target modeling formalism and not the joined modeling formalism. Section 5.5 describes how we can create a set of transformation rules in Henshin from the transformation rules in the DPF Transformation Editor. These transformation rules has a search graph structure with positive application conditions that determine the abstract syntax that a source modeling formalism one abstraction layer higher provides. Each Henshin node in a RHS graph of a rule that is specified has a reference to a target type node or arrow. For each application of a transformation rule we locate a match and create nodes and arrows with a corresponding type node and type arrow accordingly to the RHS. After the execution of all the transformation rules we can now extract these produced target modeling elements to a new target specification that conforms to a target modeling formalism. For each translated modeling element we can check if it has a corresponding type node or type arrow in the target modeling formalism.
Chapter 6

Evaluation

6.1 Evaluation of Solution

We have successfully managed to integrate Henshin with the Diagram Predicate Framework to support exogenous model transformations. This is done by including an editor for the DPF workbench that communicates with the Henshin model transformation environment to provide a model to model transformation environment for DPF models. We have extended the DPF Transformation Editor to communicate with the Henshin model transformation environment. For the solution we have utilized the strengths of the environment that it implicitly does not support. If we refer back to figure 4.1 in section 5.1 we saw that a specification is an instance of a linguistic meta-model that Henshin has no problem interpreting. The problem arises for the ontological meta-models that describes the source model together with a linguistic meta-model. Suddenly there are two models that both provides some form of abstract syntax that Henshin is required to consider when defining the content of the transformation rules. Section 5 describes how we can explicitly solve this by extending the transformation rules with application conditions. Henshin utilizes EMF’s Ecore modeling system when structuring both the left hand side and right hand side of a transformation rule. This means that Henshin supports the 2-layered modeling hierarchy that EMF provides. If we did not extend the transformation rules with application conditions accordingly to the source DSLs abstraction layer hierarchy, then Henshin would basically interpret that every DPF specification, regardless of abstraction layer is created accordingly to EMF’s 2-layered approach to meta-modeling. Because Henshin would ignore the different modeling formalisms provided by several layers of abstraction and threat all modeling elements in a specification as a node and an arrow. This would lead to a set of transformation rules that refers to the abstract syntax of the highest abstraction layer that DPF provides. This is essentially what we want for the source model, but we want to define nodes and arrows according to the modeling formalism that is one abstraction layer higher and not the highest possible abstraction layers that is a node with an arrow connected to itself. We described in the previous section that we can introduce each node and arrow with its concurrent type from one abstraction layer higher as an application condition in Henshin. This way Henshin will only locate matches for nodes and arrows that gives a valid application condition. Without the application conditions the transformation engine could potentially locate matching patterns for every single node and arrow in a source specification for a single transformation rule. These application conditions could
potentially get quite complex if the DPF Transformation Editor is extended with the possibility to specify negative and positive application condition.

The DPF Transformation Editor functions both as a support for the Henshin model transformation environment and as a solution for including support for exogenous model to model transformations in DPF. One could say that for this specific problem solution that Henshin is independent of the DPF Transformation Editor. However, this is not correct, because with the help of this tool we can make exogenous model transformations in DPF generic. This means that we could be able to transform a model specified in one DSML into a model specified in another DSML, regardless of abstraction layers. So in the case of creating transformation rules in the Henshin transformation language the DPF Transformation Editor could be considered to provide a support role. But when considering a generic model transformation for DSMLs on an arbitrary abstraction layering the tool’s role is essential. Henshin can define generic model transformations when the source and target meta-model is Ecore based models, but for our case every single DPF specification conforms to the same Ecore model. The DPF Transformation Editor provides the Henshin model transformation environment with a additional searching information through defining application conditions based on DPF specifications from higher abstraction layers.

The DPF Transformation Editor and Henshin provides a model to model transformation environment that translates a specification provided at an arbitrary layer of abstraction to another specification provided at an arbitrary layer of abstraction.

![Figure 6.1: A simplified joined modeling formalism that transformation rules refers to.](image)

Figure 6.1 explains that we create a joined specification from a source modeling formalism and a target modeling formalism from some abstraction layers. The joined specification is created independent of the two abstraction layers and is referred to when creating transformation rules in the DPF Transformation Editor.

6.2 Test case with the DPF Transformation Editor

6.3 Comparison with other editor tools

In this section we provide a comparison between the three model transformation environments that we worked with including the DPF Transformation Editor. In our solution
Chapter 6. Evaluation

we expanded the Henshin model transformation environment to be able to apply model transformations to a multi-layered meta-modeling environment like we discussed in section 6.1. It is natural that the DPF Transformation Editor will have similarities to the Henshin environment since our solutions builds heavily on this environment. But we can still compare our solution with both Henshin and other transformation tools. Table 6.1 provides an overview of the DPF Transformation Editor and the three other model transformation environments that we compared in section 4.2. We will consider only some of these elements since some of them will be explained in later subsections.

<table>
<thead>
<tr>
<th></th>
<th>AGG</th>
<th>Henshin</th>
<th>ATL</th>
<th>DPF Transform</th>
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<td>✓</td>
<td>—</td>
</tr>
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<td>in-place</td>
<td>out-place</td>
<td>out-place</td>
</tr>
</tbody>
</table>

Table 6.1: Comparing model transformation tools.

All four tools supports for an arbitrary number of both input and output elements. This means that if the tool takes a number of input models, then it produces the same number of target models. Take an ATL module as an example. It accepts a fixed number of models as input, and returns a fixed number of target models. This means that an ATL module can not generate an unknown number of target models. If there is one input model, then there will be one output model that conforms to a target meta-model.

Both AGG, DPF Transformation Editor and Henshin provides a graphical syntax to specify the transformation rules that is potentially intuitive. This is not the case for ATL, which uses a textual based approach. For ATL the users have to implement transformation rules in programming code.

The tools can be integrated with Java. For ATL the files containing the transformation rules have to be created before they can be used in a java application. In ATL this has to be a “atl” file containing a ATL module that has a list of rules. This is because the ATL transformation engine relies on a file extension with the name “atl”. Both Henshin and AGG provides an API that can be used to create transformation rules, application conditions, type graph, source graph, etc. The DPF Transformation Editor is quite different since it utilize the convenience methods that the Henshin API provides. It is possible to specify transformation rules in the DPF Transformation Editor by implementation code, but the method to generate Henshin rules requires a single production that has a left, a right and a common subgraph. We explained what a production was in section 5.

We can also see that the size of the transformation rules differ amongst the tools. The examples that are compared are different exogenous model transformations. This means
that a model transformation for all tools includes a source and target meta-model and a file containing the transformation rules. By reading the table we can see that an exogenous model transformation in the DPF Transformation Editor uses 265 kb of the storage space. This number is so unbelievably small that it will never be noticed in any modern computers. But there is one interesting thing however, that the transformation rules defined in ATL is over 60 times smaller than the DPF Transformation Editor. What this basically means is that creating model transformations through the use of textual concrete syntax is less space consuming than through the use of graphical syntax. This is only logical since the graphical syntax based transformation languages requires more storage space simply because they use graphical elements to represent the transformation rules.

6.3.1 Editing Transformation Rules

In the DPF Transformation Editor we present the transformation rules in a list of transformation rules. Each transformation rule is extended with a simplified version of the DPF Model Editor and a toolbar that contains modeling elements from a source and a target meta-model. With these modeling elements we can create and structure a searching pattern and a replacement pattern for each transformation rules. It is logical that the searching pattern and replacement pattern create modeling elements that corresponds to the source and target meta-model, since this is an exogenous model transformation between two different modeling languages. In Henshin we can choose to create transformation rules in either the tree based Henshin Model Editor or in a graph based editor. The DPF Transformation Editor that we created provides an integrated view on transformation rules, similar to Henshin and GReAT. This means that we do not provide separate editors to implicitly edit the LHS and the RHS graphs for a transformation rule like for example AGG does. This is convenient since editing is now separated in a left hand and a right hand side editor. AGG can also include a third editing window, that specifies application conditions for the rule. At first glance AGG will most likely provide a more intuitive approach to editing transformation rules compared to the integrated view that Henshin and our solution provides. The users needs to understand the principles behind graph transformations when working with either tools, but AGG might present a more intuitive approach since the tool has a clear procedure on how to create and manage new application rules. However, AGG, Henshin and DPF Transformation Editor provides a graph based approach to model transformations even though they introduce different approaches to define transformation rules. The graphical editor that AGG and Henshin provides are different in such a way that the creation of rules are different. Both Henshin and AGG has a tree based editor, but the editor works differently amongst the two tools, see figure 4.6 and 4.8 for the two editors. The graphical editor for our solution is very similar to Henshin, but does not provide any three based editor. However, when generating to Henshin transformation rule it is possible to use the tree based editor and browse through the Henshin rules and application conditions. Keep in mind that changes done to the Henshin rules might jeopardize the execution of the transformation rules for DPF specifications.

The third transformation tool we encountered in our comparison is the ATLAS Transformation Language. And while this tool is definitely not as intuitive as the the graph transformation tools, once you understand how to create transformation rules and how to work with the included meta-models, it is a good framework for working with model
transformations. However, if a user do not fully understand the Object Constraint Language (OCL), ATL is rather a hard tool to work with. Because OCL has a very leveled learning curve, since it is a declarative programming language. We are more confident in working with imperative programming languages during our studies here in Bergen. ATL provides an editor where the users can use OCL to create and modify transformation rules. ATL has a very strict way of writing transformation rules, since the tool uses a textual based approach to create transformation rules. The user has to use the predefined stereotypes defined by ATL.

6.3.2 Meta-modeling

Meta-models are initialised and handled differently amongst the four tools. The initialisation of the meta-models for Henshin and ATL is similar. Both of these tools use Ecore to create meta-models, since they are both integrated with EMF. For Henshin and ATL the user has to create one Ecore model for both the source and the target meta-model. Both of these meta-models can be imported both into Henshin and ATL. One thing that is convenient with Henshin that ATL does not provide, is that Henshin provides a list of meta-models that is available for the user. These are meta-models that can be used either as source or target meta-model. If we want to translate a instance model to an Ecore model, we can in Henshin import this Ecore meta-model from a list and use it as the target meta-model.

AGG on the other hand uses a disjoint meta-model. This means that in AGG there is something called a type graph, and in this type graph both the target and the source meta-model are defined. AGG handles consistency similar to Henshin. AGG will restrict the user to only create nodes or arrows between nodes that are specified in the type graph. Figure 4.5 in chapter 3 shows that there are created references between two meta-models. And through the use of these references, AGG can create and modify application rules to translate these two models represented in the type graph.

Through defining the abstract syntax is where our editor has its biggest advantage, since the three transformation tools that we worked with utilizes a two layered approach to modeling. First we create the abstract syntax through a meta-model and second we specify the concrete syntax through an instance model of this abstract syntax. This is also implicitly true for the DPF Transformation Editor, since every DPF specification, regardless of abstraction layer is represented as an instance model of a DPF specification one abstraction layer higher. There are some similarities to how we present meta-models like ATL and Henshin does for the transformation rules and that is through the Ecore model. There is one major difference however, and that is that our Ecore model is static and ATL and Henshin's meta-models are dynamic. And by dynamic we mean that the source meta-model and target meta-model represents the abstract syntax of some arbitrary modeling language. For the DPF Transformation Editor the source and target meta-model always corresponds to the same Ecore model and that is the common meta-model for all specifications. But with the help of application conditions in Henshin we can define an abstract syntax that the transformation rules can refer for an unlimited hierarchy layer of meta-modeling. to can adapt the Henshin transformation language to make it possible to apply model transformations to a modeling language that is specified through an unlimited hierarchy layer of meta-modeling. So one could say that every DPF specification is an instance of a common modeling language while the abstract syntax
for the modeling elements for this DPF specification are described by another DPF specification one abstraction layer higher.

### 6.3.3 Transformation Rules

We have seen that the creation of transformation rules varies over the three different tools. ATL provides a textual based approach and therefore requires multiple lines of code. The abstract syntax for the three different tools are not that different, since both Henshin and ATL utilizes the Ecore model to create meta-models and AGG creates one type graph that contains the abstract syntax for both the source and target model. The abstract syntax can be visualized either by using the tree based model editor that EMF provides or by using a tird party tool for a graphical representation of the models. The concrete syntax are obviously different between the three tools. AGG and Henshin provides a concrete graphical syntax, while ATL on the other side provides a concrete textual syntax for creating and modifying transformation rules. For both AGG and Henshin the rules can be created and modified by using a graphical editor. AGG separates the RHS and the LHS in two separate editing parts while Henshin use predefined word sequences to distinguish the two different sides. If the rules are quite large, with multiple nodes and arrows the rules presented in Henshin becomes easier to read and maintain. But both AGG and Henshin has a clear way of representing the rules and possible attached application conditions. All three tools have a left hand side and a right hand side, but are represented differently amongst the rules. Henshin and AGG use graph patterns to represent the LHS and the RHS while ATL utilizes logical expressions. In section 3 we discussed that ATL can have both declarative and imperative transformation rules. In Henshin and AGG the LHS and the RHS are represented as graphs. Where the LHS represents the pattern graph that is matched for an instance model and the RHS represents the part that should be replaced for the instance model. For ATL the LHS represents the source model while the RHS represents the target model.

Both AGG and Henshin can specify both negative and positive application conditions. These are attached to pattern graph or the LHS of a rule. These application conditions provides a true or false clause that can be used to restrict the pattern graph. For ATL these conditions are handled by OCL expressions, where one example is the if-then clause.

### 6.3.4 Rule Scheduling

ATL does the scheduling implicit, where the user has no control over the scheduling algorithm defined by the tool. The user can however influence the scheduling algorithm defined by the ATL transformation engine by designing the logic in the transformation rules to apply in a certain order. The transformation engine will first execute the declarative rules before applying the imperative section of a transformation rule. AGG and Henshin does however, give the users the possibility to influence how the transformation rules are applied. In Henshin and AGG this is handled explicitly before applying the transformation rules, where the user can change the execution order of the rule. For example the rules can be applied non-deterministic or in sequential order. To force the transformation in a sequential order could result in performance issues compared to applying the rules non-deterministically. AGG provides the users with the possibility
to organize the transformation process into several phases or layers. These layers are numbered from $0 \ldots n$, and the lower the number the higher the priority for the rule, when it is translated. This gives the users the possibility to execute rules layer by layer. In Henshin these rule scheduling mechanisms are referred to as transformation units. For this tool it is possible to specify units that supports rule iteration, both by looping through rules until there are no more changes detected or by iterating through rules for a fixed number of iterations. In Henshin it is also possible to specify an amalgamation unit, that is an unit that provides a forall-operation for the matching pattern graph. This unit has a kernel rule and multiple underlying rules that are matched as often as possible. It is clear that Henshin provides the users with quite an variety of controlling the execution of rules.

The DPF Transformation Editor does not provide the user with any control regarding how to locate matches and how transformation rules are applied. We generate a Henshin module that contains a set of transformation rules. We can manipulate the execution order of these transformation rules, but the algorithm that Henshin uses to locate matching patterns in a source model is part of the internal infrastructure of Henshin and cannot be manipulated. We can however force the transformation rules to be executed in a given order. This version of the Editor has no support defining a schedule mechanism that specifies how the rules are applied and will for now only run the transformation rules sequentially. We can decide the priority of the rules by changing the order that they appear in the DPF Transformation Editor, but this list will apply rules in sequential order. Most of the transformation tools open to the public provides solutions to manipulate the scheduling mechanism, for example ATL provides the users the possibility to define rules as lazy rules and control how they are applied. While AGG and the Henshin environment lets the users specify the scheduling mechanism over a few predefined choices.

Another thing that is special about our integration of Henshin is that locating matches are handled differently. An application condition is initially meant to restrict a transformation rule when locating matches. If application conditions are not specified for a transformation rule in some 2 layered meta-modeling transformation tool we will still locate a matching pattern that correspond to modeling elements that are described in the abstract syntax. The application condition has a vital role in our integration of Henshin, because the application conditions are checked against the DPF model that are one abstraction level higher. Without this application condition we would simply get a target DPF model that has a list of nodes and arrows that conform to the highest level of abstraction in DPF. The highest level of abstraction in DPF is always a node and an arrow, that conforms to itself. So while a 2 layered meta-modeling transformation tool would find matches in a source model that correspond to the meta-model, the DPF Transformation Editor would find matches to the linguistic meta-model and not the ontological meta-model at some level of abstraction. One could state that an application condition for a 2 layered meta-modeling transformation tool is independent of the transformation rules while our version the transformation rules are dependent on the application conditions to be able to produce a correct target model.

6.3.5 Rule Organization

ATL organizes the transformation rules inside modules, and its therefore easy to reuse these modules if applicable. This is convenient for users of ATL since this means that
all created rules can be used to form new transformation rules. Henshin provides the user with the possibility to nest or reuse rules in different scheduling mechanism or transformation units as we discussed in the last paragraph. But Henshin and therefore the DPF Transformation Editor does however not provide the user with the possibility to reuse rules in the creation of new rules like in ATL.

6.3.6 Source - Target Relationship

The DPF Transformation Editor explicitly performs an out-place model transformation. This means that we create a target model that is independent of the source model. For all matching modeling elements we locate in the source model we create in a target model. We then make sure to specify all the nodes and arrows with its corresponding type from a specification that is located one abstraction layer higher. AGG does this differently, since the source and target model are the same model. Matches are located in the source model, while the target model is updated in the same model. For an exogenous model transformation it is required that ATL produce the target model in a separate file. Henshin on the other hand provides in-place model transformations on the source model. But when we invoke the Henshin interpreter engine programmatically we can check for changes before and after executing a set of transformation rules. Henshin transformation engine requires a set of transformation rules, and a graph that contains the source model. This graph contains a list of all the modeling elements that are part of the source model. This is why we can explicitly make a model transformation out-place, by checking this list before and after the transformation and adding translated elements to a target model. The interpreter will locate matches in the source model through this graph and produce target elements to this graph.

For an exogenous transformation in ATL it is mandatory to create a new target that holds all the target model elements. Exogenous model transformation in ATL is therefore called an out-place transformations. In AGG on the other hand both source and target model is always the same model. This means that AGG performs an in-place update on its original source model. Henshin is a bit more special, because implicitly it performs in-place update on the source model. But in Henshin you can initialize variables that explicitly captures the transformed target elements and save these to a separate file in your storage unit. Note however, that this can only be done when utilizing the Henshin interpreter programmatically.

6.3.7 Directionality

To provide a graph based model transformation with the possibility to translate in both directions is not a simple task. Because then the tool will have to provide arbitrary switching between source and target models, and therefore the pattern and replacement graphs will have to be changed when they are switched. This means that the LHS and the RHS part of a transformation rules have to be switched out. This is not provided in the DPF Transformation Editor. One could do this in two steps, to first locate matches in a source model and produce a target model and then do another model transformation where the source and target part is switched. Both Henshin and AGG does not provide this since the corresponding RHS and LHS graphs are created according to the abstract syntax of the source and target model.
Its obvious that all four tools are unidirectional, since they can be executed in one direction only. That is to compute a target model from a source model. The tools requires two model transformations to be able to transform in multiple directions. Where the source and target model and meta-models switch places. But this is not how multidirectional transformations work. A multidirectional transformation can execute in both direction when performing a model transformation.

6.3.8 Tracing

Tracing in the four tools provides an unique link between a source and a target. The source represents the matched part while the target represents the generated or replacement part. All three tools provides dedicated support for traceability. But these traceable links are handled differently amongst the tools. For ATL the trace model works as a storage location and automatically creates trace links between source and target elements. These traceable links are internally used by the ATL transformation engine when executing a model transformation. But we explained in section 3 that these trace links can be explicitly captured by creating transformation rules that generates a collection of trace links in a separate trace file. Henshin does this differently, because tracing is controlled by the users. Henshin has a dedicated Trace Model that can be imported to the Henshin module as an Ecore model. The trace model in Henshin are automatically created when executing rules, but the user have to manually assign the traceable links inside the transformation rules. The traces in Henshin are translated when a rule is executed, and therefore the user has to be aware of this when using these traces in other rules, since this could lead to the creation of multiple traceable links between the same elements. The DPF Transformation Editor defines a traceable link with source and target modeling elements differently amongst nodes and arrows. For DPF models nodes and arrows are defined by the EClass modeling element that Ecore provides. Tracing in AGG plays a vital role to executing model transformations. Traceable elements are created similar to any other elements when initializing the type graph. With traceable links between the source and the target elements, AGG can be certain that elements are transformed. The traceable link in AGG ensures that a match in the pattern graph is only matched once. If we do not create a traceable link between source and target elements in AGG, the rules will be applied an endless amount of times. Tracing amongst the three different tools are different in such a way that it is required for exogenous model transformations for AGG and ATL. In ATL the traceable links are created automatically and cannot be controlled by the users, while in AGG the traceable links are created as bridges between source and target elements. For Henshin the Trace model is optional.

6.3.9 Translating the instance model

When ATL transformation language executes the application rules for the model to model transformation, a new model instance is created for the target model. This means that the source model is independent of the target model. Where Henshin and AGG performs in-place model to model transformations. This means that they both operate on an instance model of the source meta-model, and translates inside this instance model. On the other side, for ATL this is not needed, since both the source and target model are kept as separated files. This is also possible to achieve with Henshin. If the user
programmatically invoke the Henshin Interpreter the target model can be forced to be saved in a newly created file. Henshin will still do an in-place model transformation, but it is possible to save the translated object in a separate file. It is then possible to perform an in-place transformation in Henshin while saving the target instance model in a separate file. The DPF Transformation Editor utilize the strengths of Henshin to perform an in-place model transformation of a source model and explicitly creates a target model based on the results of this source model. All four approaches can however give the same result. In AGG and Henshin the users just need to make sure to delete unwanted elements from the translated host graph. This is different in the DPF Transformation Editor since we produce a target graph structure for each matching graph structure and specifies the target graph structures in a separate target model.
Chapter 7

Conclusion

There are several model transformation environments available that provides model to model transformations. These environments are designed accordingly to different approaches to model transformations. In this thesis we have explored three different model transformation environments that could expand the DPF Workbench with model to model transformation. We integrated a version of the DPF Transformation Editor that integrates the Henshin transformation language and engine to provide an exogenous model transformation environment for DPF. Henshin proved to be a viable transformation language that facilitates a model to model transformation environment for the DPF Workbench. In this thesis we have explained that Henshin can be extended with application conditions to perform model transformations on models described through arbitrary layers of abstractions.

- Application conditions to specify the abstract syntax from a DPF specification one abstraction layer higher.
- Requires a traceable link between each source and target modeling elements. This traceable link is utilized in three different aspects when integrating Henshin with the DPF Transformation Editor.
  1. Specifies that the engine only translates a matching pattern once.
  2. Defines a correspondence between source and target modeling elements.
  3. Reusable in other rules if the source and target element are used to define the LHS and RHS graph.

For an exogenous model transformation Henshin requires a traceable link between source and target modeling elements not only to specify the correspondence between two modeling objects, but also to reuse the source and target node of this traceable links in other rules. These modeling objects represents either a node or an arrow in a DPF specification. For a transformation rule when a traceable link is first established it is actually transformed like any other graph structure initialized by the RHS graph. Now we can use this traceable link if for example produced modeling elements are part of the LHS and RHS graph in other transformation rules. Note that to use a traceable link in other rules arises a potential dependency issue. The reason for this is because in this solution we designed the application control mechanism to apply transformation rules
in a sequential order. If the application control utilizes a non-deterministic mechanism to apply rules then the target model would in worst case not produce any result. Since one rule requires a traceable link that should be initialized in another rule. However, to apply a set of transformation rules non-deterministically is convenient if the source model contains a dense graph, which should not be an issue since DPF specifications are human made.

The integration of Henshin with DPF allows for the possibility to translate a DPF specification to a DPF specification that conforms to another modeling formalism. The solution still requires more testing on different exogenous model transformation scenarios, but editor should be able to create a set of transformation rules in Henshin based on a source and target modeling formalism.

7.1 Future Work

There are still some work that is required to do before the DPF Transformation Editor becomes a mature system that can provides model to model transformations.

7.1.1 Endogenous Model Transformations

In this thesis we present an integration of Henshin that supports exogenous model transformations over different layers of abstraction, but the DPF Transformation Editor should be extended with endogenous model transformations. This can also be achieved by using Henshin, but an endogenous model transformation solution is done differently in Henshin compared to an exogenous model transformation. For Henshin we can utilize the double pushout approach to first locate a match, then delete modeling elements that are uniquely part of the LHS. The next pushout consist of inserting modeling elements that are uniquely part of the RHS. While these two operations are performed, modeling elements that is part of both the LHS and the RHS are preserved. This meant that we do not need traceable links to provide endogenous model transformation on DPF specifications in Henshin.

7.1.2 Making the Model Transformations constraint aware

The DPF Transformation Editor does at this moment not provide model to model transformation that is constraint aware for the source and target modeling formalism. Basically this means that we do not consider the constraints that is defined in the abstract syntax of the source and target meta-model. Figure 7.1 explains how we can do this.
We could extend the joined modeling formalism with constraints. This means that we have to create the constraints for both the source modeling formalism and the target modeling formalism in the joined modeling formalism. This means that we can make transformation rules in the DPF Transformation Editor that also includes the possibility to define the RHS with constraints based on constraints from the LHS. This is particularly convenient if we want to transform one modeling formalism into another modeling formalism.

7.1.3 Verification of target modeling formalism predicates

When the target model are finished with the transformation the corresponding predicates from the target modeling formalism requires verification. This can be achieved by searching through every single node and arrow in the target specification and make sure that the predicates are fulfilled with the target modeling formalism one abstraction layer higher.
Bibliography


Bibliography